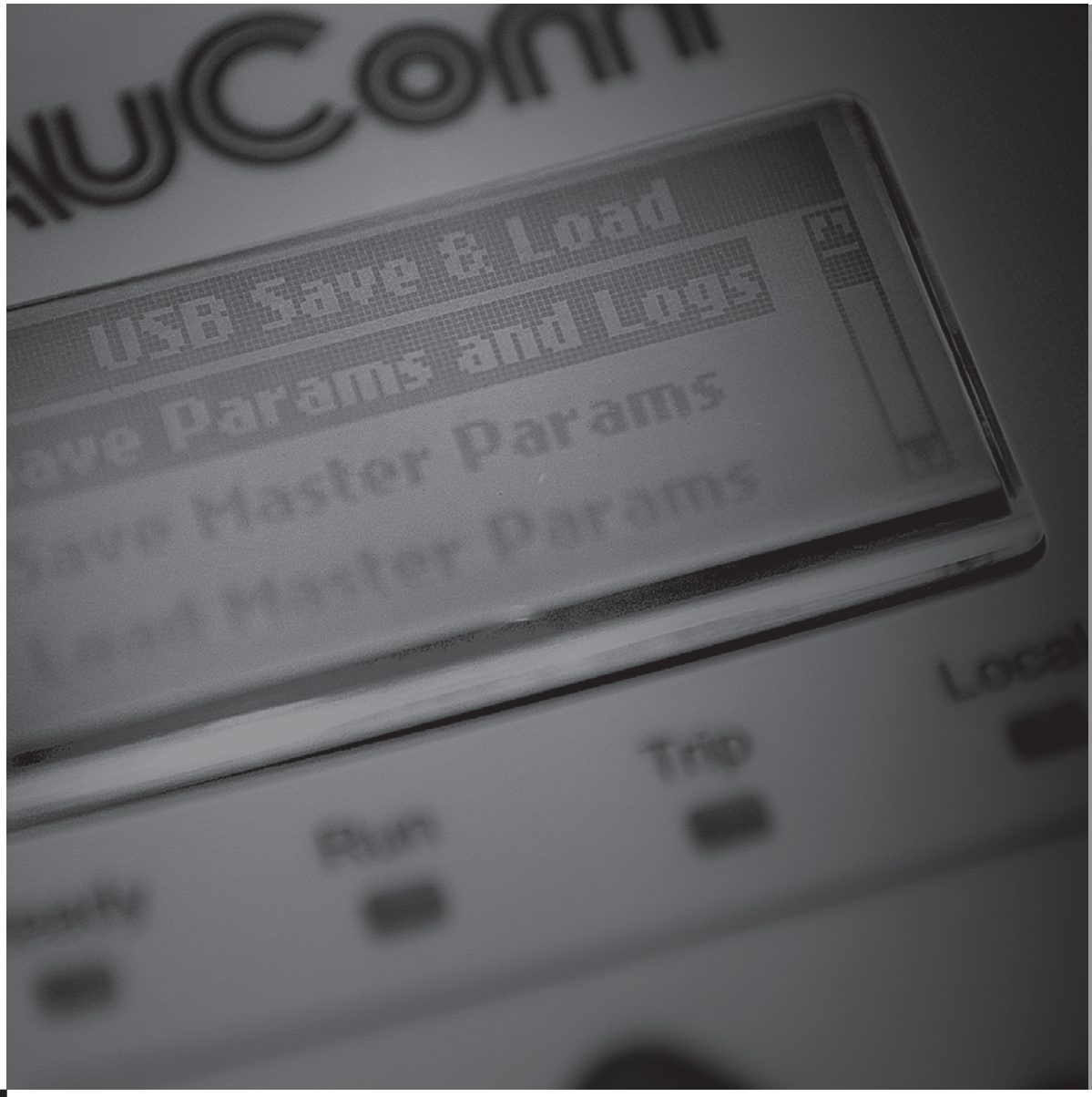
USER MANUAL

EMX4i Soft Starter



RIGHT FROM THE START

AuCom
MOTOR CONTROL SPECIALISTS

Contents

1. About This Manual

WARNING
Indicates a hazard that may cause personal injury or death.

CAUTION
Indicates a hazard that may damage the equipment or installation.

NOTE
Provides helpful information.

1.1 Disclaimer

The examples and diagrams in this manual are included solely for illustrative purposes.

The information contained in this manual is subject to change at any time and without prior notice. In no event will responsibility or liability be accepted for direct, indirect or consequential damages resulting from the use or application of this equipment.

2. Caution Statements

Caution Statements cannot cover every potential cause of equipment damage but can highlight common causes of damage. It is the installer's responsibility to read and understand all instructions in this manual prior to installing, operating or maintaining the equipment, to follow good electrical practice including applying appropriate personal protective equipment and to seek advice before operating this equipment in a manner other than as described in this manual.

NOTE

The EMX4i soft starter is not user serviceable. The unit should only be serviced by authorised service personnel. Unauthorised tampering with the unit will void the product warranty.

2.1 Electrical shock risk

WARNING – ELECTRICAL SHOCK RISK

The voltages present in the following locations can cause severe electric shock and may be lethal:

- AC supply cables and connections
- Output cables and connections
- Many internal parts of the starter

The AC supply must be disconnected from the starter using an approved isolation device before any cover is removed from the starter or before any servicing work is performed.

SHORT CIRCUIT

The EMX4i is not short circuit proof. After severe overload or short circuit, the operation of the EMX4i should be fully tested by an authorised service agent.

GROUNDING AND BRANCH CIRCUIT PROTECTION

It is the responsibility of the user or person installing the EMX4i to provide proper grounding and branch circuit protection according to local electrical safety codes.

FOR YOUR SAFETY

- The STOP function of the soft starter does not isolate dangerous voltages from the output of the starter. The soft starter must be disconnected by an approved electrical isolation device before accessing electrical connections.

- Soft starter protection features apply to motor protection only. It is the user's responsibility to ensure safety of personnel operating machinery.
- The soft starter is a component designed for integration within an electrical system; it is therefore the responsibility of the system designer/user to ensure the system is safe and designed to comply with relevant local safety standards.

2.2 Unexpected Operation

WARNING – ACCIDENTAL STARTS

In some installations, accidental starts may pose an increased risk to safety of personnel or damage to the machines being driven. In such cases, it is recommended that the power supply to the soft starter is fitted with an isolating switch and a circuit-breaking device (eg power contactor) controllable through an external safety system (eg emergency stop, fault detector).

WARNING – STARTER MAY START OR STOP UNEXPECTEDLY

The EMX4i will respond to control commands from various sources, and could start or stop unexpectedly. Always disconnect the soft starter from mains voltage before accessing the starter or load.

WARNING – DISCONNECT MAINS BEFORE ACCESSING STARTER OR LOAD

The soft starter has built-in protections which can trip the starter in the event of faults and thus stop the motor. Voltage fluctuations, power cuts and motor jams may also cause the motor to trip.

The motor could restart after the causes of shutdown are rectified, which may be dangerous for personnel. Always disconnect the soft starter from mains voltage before accessing the starter or load.

CAUTION – MECHANICAL DAMAGE FROM UNEXPECTED RESTART

The motor could restart after the causes of shutdown are rectified, which may be dangerous for certain machines or installations. In such cases, it is essential that appropriate arrangements are made against restarting after unscheduled stops of the motor.

2.3 Avertissements à l'attention des clients canadiens

AVERTISSEMENT

L'icône AVERTSSEMENT ci-contre signale les informations concernant des risques pouvant entraîner des blessures graves, voire mortelles. Pour votre sécurité, veuillez consulter les avertissements sur cette page ou demander une copie du présent manuel en français auprès de votre distributeur local.

AVERTISSEMENT – RISQUE DE CHOC ÉLECTRIQUE

Les zones suivantes sont soumises à des tensions pouvant provoquer des risques de chocs électriques graves, voire mortels :

- Raccordement et câbles d'alimentation AC
- Câbles et raccordements de sortie
- De nombreuses pièces internes du démarreur

L'alimentation AC doit être déconnectée du démarreur au moyen d'un dispositif d'isolation agréé avant de retirer des capots ou avant de procéder à des travaux d'entretien.

PAR SÉCURITÉ

- La fonction STOP du démarreur progressif n'isole pas des tensions dangereuses de la sortie du démarreur. Le démarreur progressif doit être déconnecté par un dispositif d'isolement électrique approprié avant d'accéder aux connexions électriques.
- Les fonctions de protection du démarreur progressif ne concernent que la protection du moteur. Il relève de la responsabilité de l'utilisateur d'assurer la sécurité des personnes travaillant sur les machines.
- Le démarreur progressif est un appareil conçu pour s'intégrer dans un système électrique ; il relève donc de la responsabilité du concepteur ou de l'utilisateur de veiller à ce que ce système soit sûr et conçu selon les normes de sécurité locales en vigueur.

AVERTISSEMENT – DÉMARRAGES ACCIDENTELS

Dans certaines installations, des démarrages accidentels peuvent provoquer un risque supplémentaire pour la sécurité des personnes ou endommager les machines contrôlées. Dans de tels cas, il est recommandé de doter l'alimentation du démarreur progressif d'un interrupteur d'isolement et d'un coupe-circuit (par exemple, un disjoncteur) contrôlable à partir d'un système de sécurité externe (par exemple, un arrêt d'urgence, un détecteur de défaut).

AVERTISSEMENT – LE DÉMARREUR PEUT DÉMARRER OU S'ARRÊTER À TOUT MOMENT

L'EMX4i répond aux commandes de contrôle de différentes origines et peut par conséquent démarrer ou s'arrêter à tout moment. Toujours déconnecter le démarreur de la tension secteur avant d'accéder au démarreur ou à la charge.

AVERTISSEMENT – DÉCONNECTER L'ALIMENTATION PRINCIPALE AVANT D'ACCÉDER AU DÉMARREUR OU À LA CHARGE

Le démarreur progressif comporte des protections intégrées qui peuvent déclencher des mises en sécurité dans l'éventualité de défauts et ainsi arrêter le moteur. Des fluctuations de tension, des coupures d'alimentation et des blocages du moteur peuvent produire des mises en sécurité de celui-ci.

Le moteur pourrait redémarrer une fois que les causes de l'arrêt ont été résolues, ce qui pourrait mettre en danger le personnel. Toujours déconnecter le démarreur de la tension secteur avant d'accéder au démarreur ou à la charge.

AVERTISSEMENT

Ne pas appliquer la tension du secteur au démarreur tant que tout le câblage n'est pas terminé.

AVERTISSEMENT

Toujours appliquer la tension de commande avant (ou en même temps que) la tension secteur.

AVERTISSEMENT

Lors du raccordement de l'EMX4i en connexion 6 fils, toujours installer un contacteur principal ou un disjoncteur magnéto-thermique à bobine de déclenchement.

3. System Design

3.1 Feature List

Streamlined setup process

- Configuration profiles for common applications
- Built-in metering and inputs/outputs

Easy to understand interface

- Multi-language menus and displays
- Descriptive option names and feedback messages
- Real-time performance graphs

Supports energy efficiency

- IE3 compatible
- 99% energy efficient when running
- Internal bypass
- Soft start technology avoids harmonic distortion

Extensive range of models

- 24 A to 580 A (nominal)
- 200 VAC to 525 VAC
- 380 VAC to 600 VAC
- Inside delta installation

Versatile starting and stopping options

- Adaptive Control
- Constant Current
- Current Ramp
- Timed voltage ramp soft stop
- Coast To Stop
- DC Brake
- Soft Brake

Customisable protection

- Motor overload
- Excess Start Time
- Undercurrent
- Overcurrent
- Current imbalance
- Input Trip
- Motor thermistor

Extensive input and output options

- Remote control inputs
  (2 x fixed, 2 x programmable)
- Relay outputs
  (1 x fixed, 2 x programmable)
- Analog output

Optional features for advanced applications

- Smart cards
- Communication modules:
  DeviceNet, Ethernet/IP, Modbus RTU, Modbus TCP, Profibus, Profinet

3.2 Model Selection

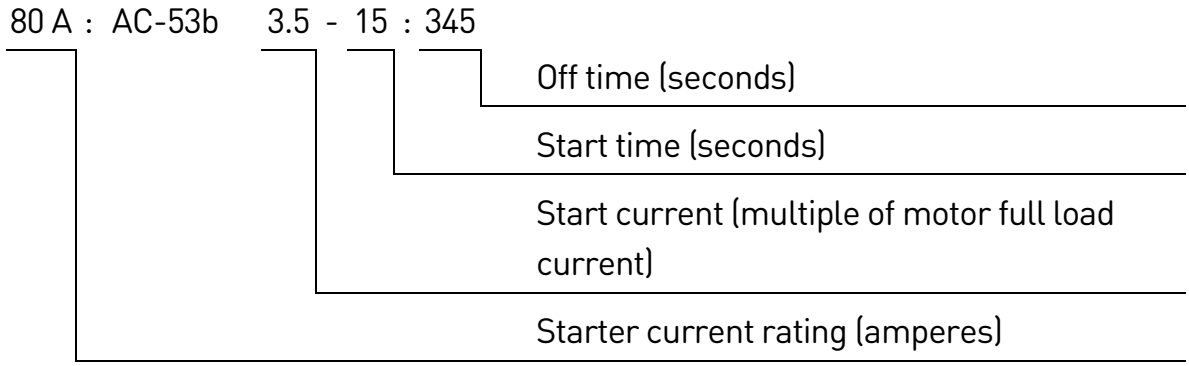
Starter sizing

The soft starter must be the correct size for the motor and the application.

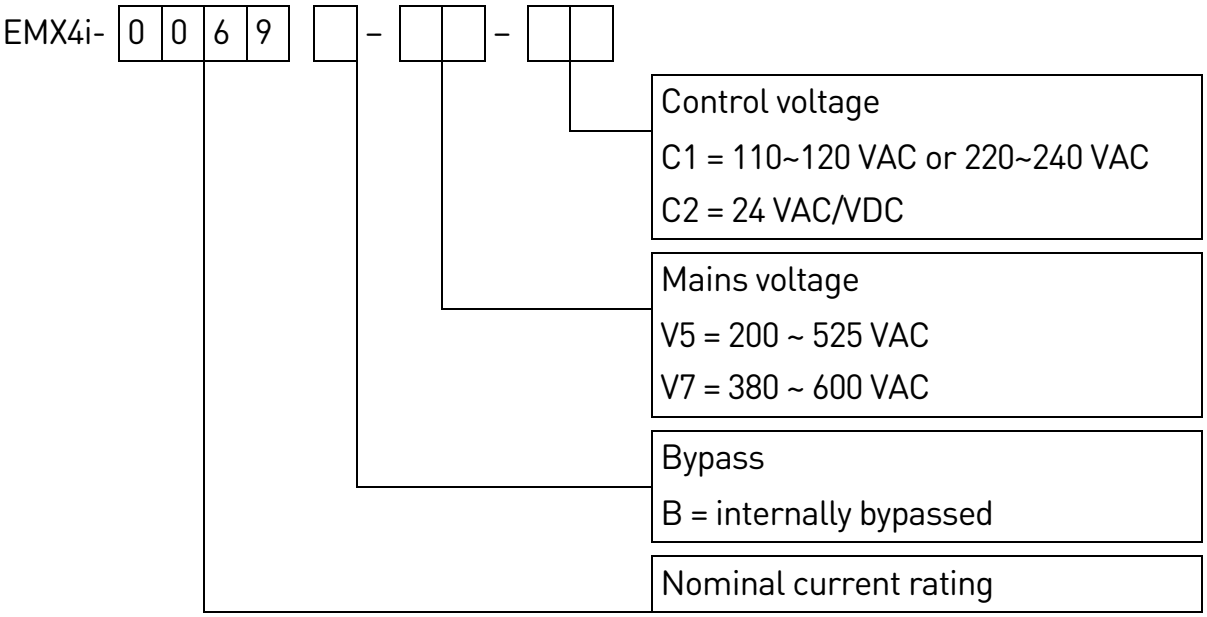
Select a soft starter that has a current rating at least equal to the motor's full load current (nameplate) rating, at the start duty.

The soft starter's current rating determines the maximum motor size it can be used with. The soft starter's rating depends on the number of starts per hour, the length and current level of the start, and the amount of time the soft starter will be off (not passing current) between starts.

The soft starter's current rating is only valid when used in the conditions specified in the AC53b code - the soft starter may have a higher or lower current rating in different operating conditions.



3.3 Model Code

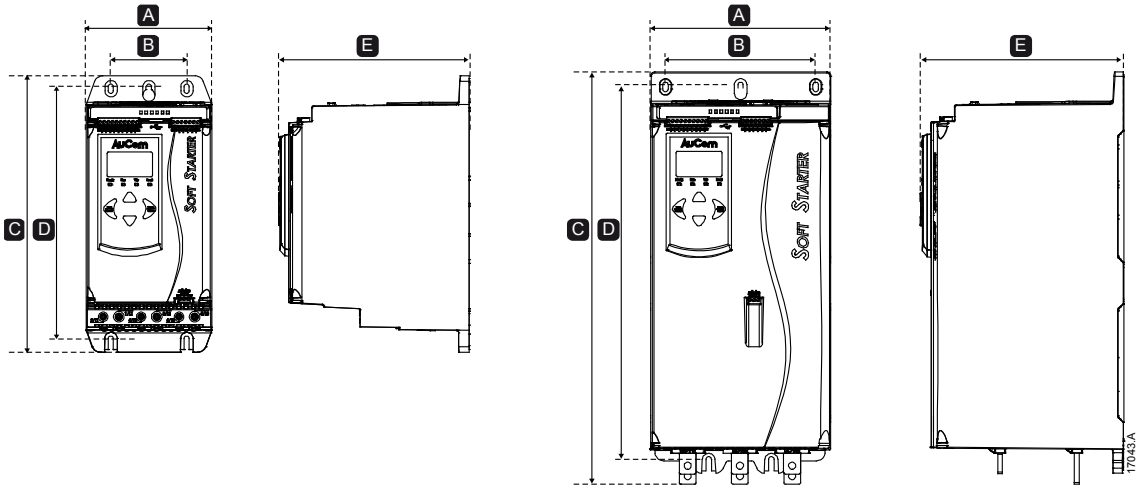


3.4 Current Ratings

	AC53b 3.0-10:350 40 ºC <1000 metres	AC53b 3.5-15:345 40 ºC <1000 metres	AC53b 4.0-10:350 40 ºC <1000 metres	AC53b 4.0-20:340 40 ºC <1000 metres
EMX4i-0024B	24	20	18	16
EMX4i-0042B	42	34	31	27
EMX4i-0052B	52	41	39	35
EMX4i-0064B	64	60	62	52
EMX4i-0069B	69	69	69	62
	AC53b 3.0-10:590 40 ºC <1000 metres	AC53b 3.5-15:585 40 ºC <1000 metres	AC53b 4.0-10:590 40 ºC <1000 metres	AC53b 4.0-20:580 40 ºC <1000 metres
EMX4i-0105B	105	85	83	68
EMX4i-0115B	115	107	103	85
EMX4i-0135B	135	129	125	102
EMX4i-0184B	184	142	138	115
EMX4i-0200B	200	170	163	137
EMX4i-0229B	229	193	171	151
EMX4i-0250B	250	243	227	204
EMX4i-0352B	352	285	264	210
EMX4i-0397B	397	323	297	227
EMX4i-0410B	410	410	410	381
EMX4i-0550B	550	525	500	423
EMX4i-0580B	580	580	550	470

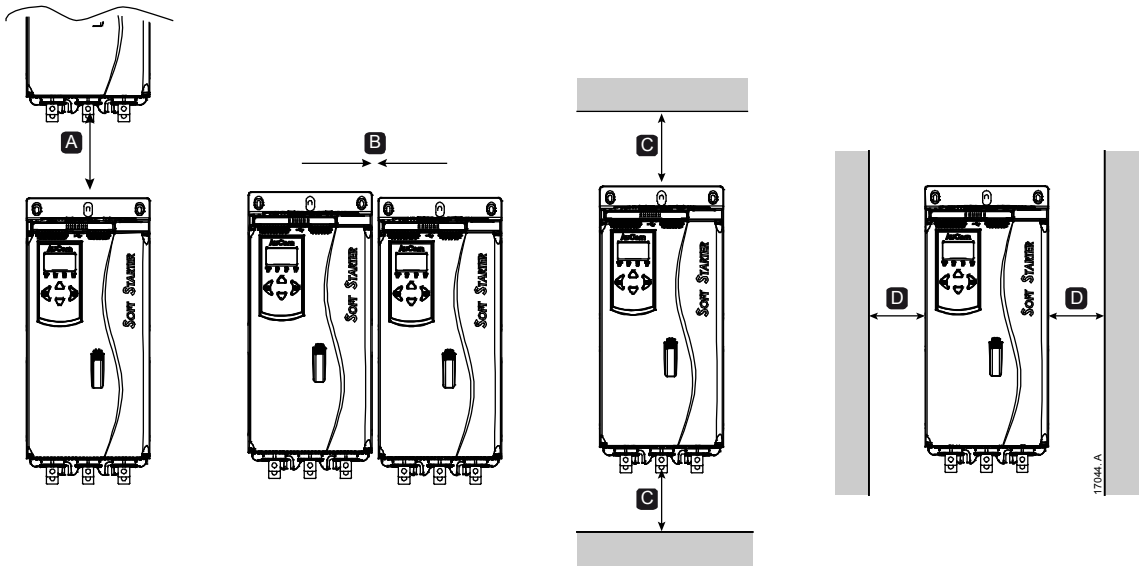
For operating conditions not covered by these ratings charts, download AuCom's free WinStart selection application, or contact your local supplier.

3.5 Dimensions and Weights



	Width mm (inch)		Height mm (inch)		Depth mm (inch)	Weight kg (lb)
	A	B	C	D	E	
EMX4i-0024B						4.8
EMX4i-0042B						(10.7)
EMX4i-0052B						4.9
EMX4i-0064B	152	92	336	307	231	(10.9)
EMX4i-0069B	(6.0)	(3.6)	(13.2)	(12.1)	(9.1)	
EMX4i-0105B						5.5
EMX4i-0115B						(12.1)
EMX4i-0135B						
EMX4i-0184B						
EMX4i-0200B			495			12.7
EMX4i-0229B	216	180	(19.5)	450	243	(28.0)
EMX4i-0250B	(8.5)	(7.1)		(17.7)	(9.6)	
EMX4i-0352B						15.5
EMX4i-0397B			523			(34.2)
EMX4i-0410B			(20.6)			
EMX4i-0550B						19.0
EMX4i-0580B						(41.9)

3.6 Physical Installation



Between starters		Solid surfaces	
A	B	C	D
> 100 mm (3.9 inch)	> 10 mm (0.4 inch)	> 100 mm (3.9 inch)	> 10 mm (0.4 inch)

3.7 Accessories

Expansion Cards

The EMX4i offers expansion cards for users requiring additional inputs and outputs or advanced functionality. Each EMX4i can support a maximum of one expansion card.

- **Smart Cards**

The smart card has been designed to support integration with pumping applications and provides the following additional inputs and outputs:

- 3 x digital inputs
- 3 x 4-20 mA transducer inputs
- 1 x RTD input
- 1 x USB-B port
- Remote keypad connector

- **Communication Expansion Cards**

EMX4i soft starters support network communication via easy-to-install communications expansion cards. Each communications card includes a remote keypad connector port.

Available protocols:

DeviceNet, Ethernet/IP, Modbus RTU, Modbus TCP, Profibus, Profinet.

Remote Keypad

EMX4i starters can be used with a remote keypad, mounted up to 3 metres away from the starter. Each expansion card includes a keypad connection port, or a dedicated keypad connector card is available.

Finger Guard Kit

Finger guards may be specified for personnel safety. Finger guards fit over the soft starter terminals to prevent accidental contact with live terminals. Finger guards provide IP20 protection when used with cable of diameter 22 mm or greater.

Finger guards are compatible with models EMX4i-0184B ~ EMX4i-0580B.

WinMaster Starter Management Software

WinMaster PC software can provide real-time or offline management of all AuCom soft starters.

- For real-time management in a network of up to 99 starters, WinMaster must connect to the EMX4i via a Modbus TCP or Modbus RTU card. WinMaster can monitor, control and program the starter across the network.
- For offline management, a configuration file generated in WinMaster can be loaded into the starter via the USB port.

3.8 Main Contactor

A main contactor is recommended to protect the soft starter from voltage disturbances on the network, while stopped. Select a contactor with an AC3 rating greater than or equal to the full load current rating of the connected motor.

Use the main contactor output (33, 34) to control the contactor.

WARNING

When connecting the EMX4i in inside delta configuration, always install a main contactor or shunt trip circuit breaker.

3.9 Circuit Breaker

A shunt trip circuit breaker may be used instead of a main contactor to isolate the motor circuit in the event of a soft starter trip. The shunt trip mechanism must be powered from the supply side of the circuit breaker or from a separate control supply.

3.10 Power Factor Correction

If power factor correction is used, a dedicated contactor should be used to switch in the capacitors.

To use the EMX4i to control power factor correction, connect the PFC contactor to a programmable relay set to Run. When the motor reaches full speed, the relay will close and power factor correction will be switched in.

CAUTION
Power factor correction capacitors must be connected to the input side of the soft starter. Connecting power factor correction capacitors to the output side will damage the soft starter.

3.11 Power Supply Fuses

Fuses may be installed to protect the soft starter or the installation.

Type 1 Coordination

Type 1 coordination requires that, in the event of a short circuit on the output side of a soft starter, the fault must be cleared without risk of injury to personnel. There is no requirement that the soft starter must remain operational after the fault.

HRC fuses (such as Ferraz/Mersen AJT fuses) can be used for Type 1 coordination according to IEC 60947-4-2 standard.

Type 2 Coordination

Type 2 coordination requires that in the event of a short circuit on the output side of a soft starter, the fault must be cleared without risk of injury to personnel or damage to the soft starter.

Semiconductor fuses for Type 2 circuit protection are additional to HRC fuses or MCCBs that form part of the motor branch circuit protection.

Fuse Selection for Type 2 Coordination

Type 2 coordination is achieved by using semiconductor fuses. These fuses must be able to carry motor start current and have a total clearing I^2t < the I^2t of the soft starter SCRs.

CAUTION
DC Brake: A high brake torque setting can result in peak currents up to motor DOL being drawn while the motor is stopping. Ensure protection fuses installed in the motor branch circuit are selected appropriately.

When selecting semiconductor fuses for EMX4i, use the I^2t values in the table.

For further information on selecting semiconductor fuses, contact your local distributor or download the fuse selection application note from www.aucom.com.

I^2t values for Type 2 coordination

Model	SCR I^2t (A^2s)
EMX4i-0024B	1150
EMX4i-0042B	8000
EMX4i-0052B	
EMX4i-0064B	15000
EMX4i-0069B	
EMX4i-0105B	80000
EMX4i-0115B	
EMX4i-0135B	125000
EMX4i-0184B	320000
EMX4i-0200B	
EMX4i-0229B	
EMX4i-0250B	
EMX4i-0352B	202000
EMX4i-0397B	
EMX4i-0410B	320000
EMX4i-0550B	781000
EMX4i-0580B	

3.12 Specifications

Supply

Mains voltage (L1, L2, L3)

- EMX4i-xxxx-V5 ..... 200 VAC ~ 525 VAC (± 10%)
- EMX4i-xxxx-V7 ..... 380 VAC ~ 600 VAC (± 10%)
- EMX4i-xxxx-V7 ..... 380 VAC ~ 690 VAC (± 10%)
  ..... (earthed star supply system only)

Control voltage (A1, A2, A3)

- EMX4i-xxxxB-xx-C1 (A1, A2) ..... 110 ~ 120 VAC (+10%/-15%), 600 mA
- EMX4i-xxxxB-xx-C1 (A2, A3) ..... 220 ~ 240 VAC (+10%/-15%), 600 mA
- EMX4i-xxxxB-xx-C2 (A1, A3) ..... 24 VAC/VDC (± 20%), 2.8 A

Mains frequency ..... 45 Hz ~ 66 Hz

Rated insulation voltage to earth ..... 600 VAC

Rated impulse withstand voltage ..... 4 kV

Form designation .....
..... Bypassed or continuous, semiconductor motor starter form 1

Short circuit capability

Coordination with semiconductor fuses ..... Type 2

Coordination with HRC fuses ..... Type 1

Electromagnetic capability (compliant with EU Directive 2004/108/EC)

EMC Immunity ..... IEC 60947-4-2

EMC Emissions ..... IEC 60947-4-2 Class B

Inputs

Input rating ..... Active 24 VDC, 8 mA approx

Motor thermistor (B4, B5) ..... Trip >3.6 kΩ, reset <1.6kΩ

Outputs

Relay outputs ..... 10A @ 250 VAC resistive, 5A @ 250 VAC AC15 pf 0.3

- Main contactor (33, 34) ..... Normally Open
- Relay output A (41, 42, 44) ..... Changeover
- Relay output B (53, 54) ..... Changeover

Analog output (21, 22)

- Maximum load ..... 600 Ω (12 VDC @ 20 mA)
- Accuracy ..... ± 5%

Environmental

Operating temperature ..... -10 ˚C to 60 ˚C, above 40 ˚C with derating
Storage temperature ..... -25 °C to + 60 °C
Operating Altitude ..... 0 - 1000 m, above 1000 m with derating
Humidity ..... 5% to 95% Relative Humidity
Pollution degree ..... Pollution Degree 3
Vibration ..... IEC 60068-2-6
Protection
EMX4i-0024B ~ EMX4i-0135B IP20
EMX4i-0184B ~ EMX4i-0580B IP00

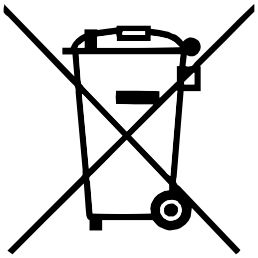
Heat dissipation

During Start ..... 4.5 watts per ampere
During Run
EMX4i-0024B ~ EMX4i-0052B ..... ≤ 35 watts approx
EMX4i-0064B ~ EMX4i-0135B ..... ≤ 50 watts approx
EMX4i-0184B ~ EMX4i-0250B ..... ≤ 120 watts approx
EMX4i-0352B ~ EMX4i-0580B ..... ≤ 140 watts approx

Certification

RCM ..... IEC 60947-4-2
CE ..... IEC 60947-4-2

3.13 Disposal Instructions



Equipment containing electrical components may not be disposed of together with domestic waste.

It must be collected separately as electrical and electronic waste according to local and currently valid legislation.

4. Installation

WARNING
Do not apply mains voltage to the starter until all wiring is complete.

WARNING
Always apply control voltage before (or with) mains voltage.

4.1 Command Source

The EMX4i can be started and stopped via the digital inputs, remote keypad, communication network, smart card or scheduled auto-start/stop. The command source can be set via the Setup Tools, or using parameter 1A *Command Source*.

4.2 Basic Setup

Setup Procedure Overview

1. Mount the soft starter (refer to *Physical Installation* on page 12 for details).
2. Connect control wiring (refer to *Input Terminals* on page 19 for details).
3. Apply control voltage to the starter.
4. Configure your application:
    1. Press MENU to open the Menu.
    2. Press ▶ to open the Quick Setup menu.
    3. Scroll through the list to find your application, then press ▶ to begin the configuration process (refer to *Quick Setup* on page 26 for details).
5. If your application is not listed in Quick Setup:
    1. Press ◀ to return to the Menu.
    2. Use ▼ to scroll to Main Menu and press ▶.
    3. Scroll to Motor Details and press ▶, then press ▶ again to edit parameter 1B *Motor Full Load Current*.
    4. Set parameter 1B to match the motor's full load current (FLC).
    5. Press ▶ to save the setting.
6. Close the Menu by pressing ◀ repeatedly.
7. (Optional) Use the built-in simulation tools to check that the control wiring is connected correctly (refer to *Run Simulation* on page 28).
8. Connect the motor cables to starter output terminals 2/T1, 4/T2, 6/T3.
9. Connect mains supply cables to starter input terminals 1/L1, 3/L2, 5/L3 (refer to *Power Terminations* on page 23).

The soft starter is now ready to control the motor.

4.3 Inputs

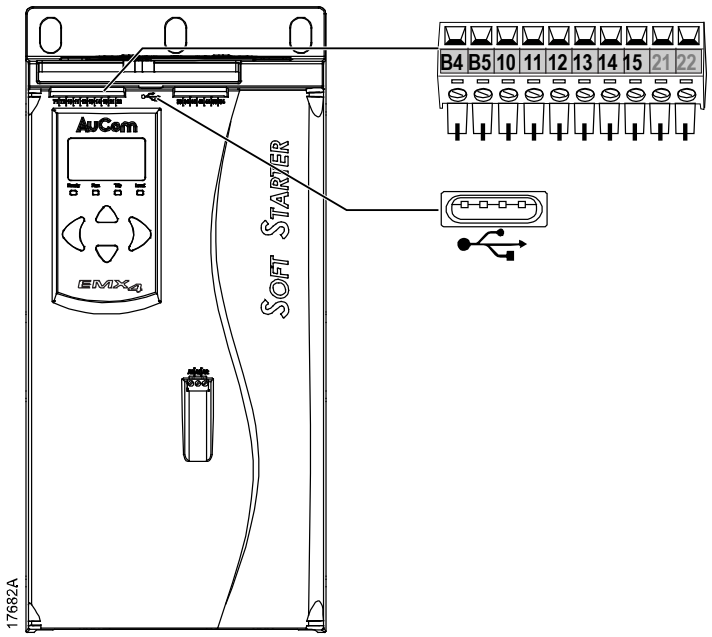
CAUTION

The control inputs are powered by the soft starter. Do not apply external voltage to the control input terminals.

NOTE

Cables to the control inputs must be segregated from mains voltage and motor cabling.

Input Terminals



B4, B5	Motor thermistor input
10, 11	Reset input
11, 12	Start/stop input
13, 14	Programmable input A (default = Input Trip (N/O))
13, 15	Programmable input B (default = Input Trip (N/O))
⇽	USB port

Motor Thermistor

Motor thermistors can be connected directly to the EMX4i. The soft starter will trip when the resistance of the thermistor circuit exceeds approximately 3.6 kΩ or falls below 20 Ω.

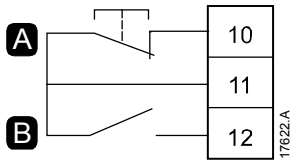
The thermistors must be wired in series. The thermistor circuit should be run in screened cable and must be electrically isolated from earth and all other power and control circuits.

NOTE

The thermistor input is disabled by default, but activates automatically when a thermistor is detected. If thermistors have previously been connected to the EMX4i but are no longer required, use the Thermistor Reset function to disable the thermistor. Thermistor Reset is accessed via the Setup Tools.

Start/Stop

The EMX4i requires two-wire control.



A	Reset
B	Start/Stop

NOTE

The EMX4i will only accept commands from the control inputs if parameter 1A *Command Source* is set to Digital Input.

Reset/Starter Disable

The reset input (10, 11) is normally open by default. The EMX4i will not perform a start if the reset input is open. The display will show "Not Ready".

If the reset input opens while the EMX4i is running, the starter will remove power and allow the motor to coast to stop.

NOTE

The reset input can be configured for normally closed operation. Use parameter 7I *Reset/Enable Logic*.

Programmable Inputs

The programmable inputs (13, 14 and 13, 15) allow external equipment to control the starter.

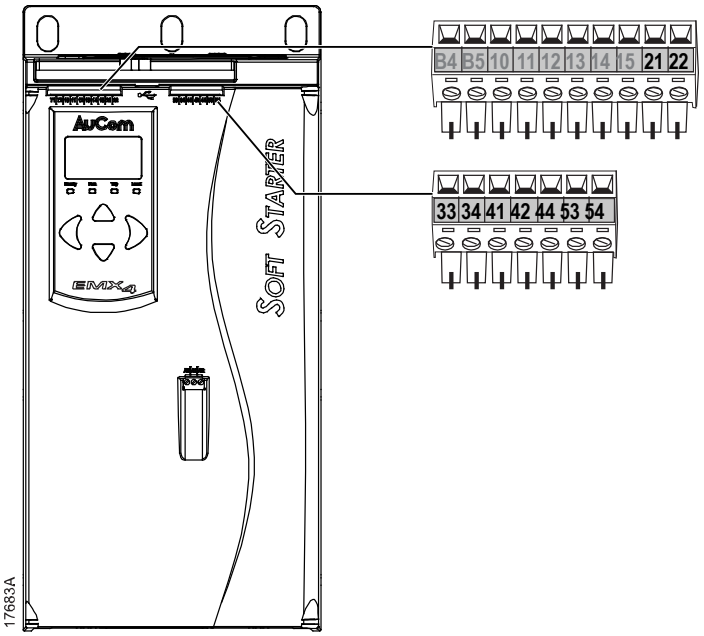
The operation of the programmable inputs is controlled by parameters 7A ~ 7H.

USB Port

The USB port can be used to upload a configuration file, or download parameter settings and event log information from the starter. Refer to *USB Save & Load* on page 29 for details.

4.4 Outputs

Output Terminals



21, 22	Analog output
33, 34	Main contactor output
41, 42, 44	Relay output A (default = Run)
53, 54	Relay output B (default = Run)

Analog Output

The EMX4i has an analog output, which can be connected to associated equipment to monitor motor performance.

The operation of the analog output is controlled by parameters 9A ~ 9D.

Main Contactor Output

The main contactor output (33, 34) closes as soon as the soft starter receives a start command and remains closed while the soft starter is controlling the motor (until the motor starts a coast to stop, or until the end of a soft stop). The main contactor output will also open if the soft starter trips.

CAUTION
Some electronic contactor coils are not suitable for direct switching with PCB mount relays. Consult the contactor manufacturer/supplier to confirm suitability.

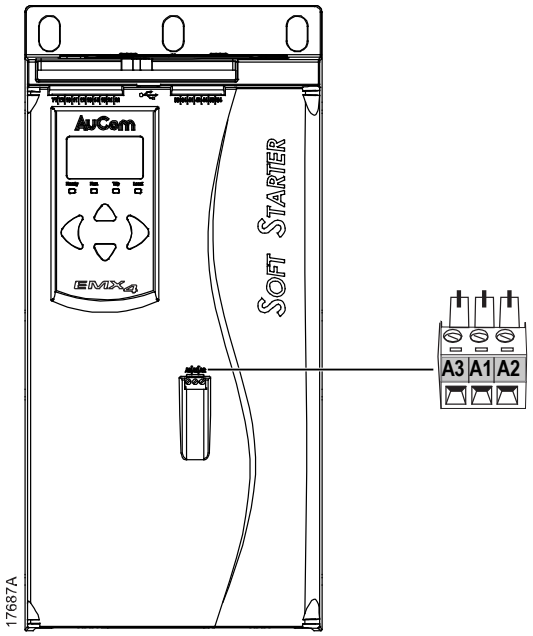
Programmable Outputs

The programmable outputs (41, 42, 44 and 53, 54) can report the status of the starter, or can be used to control associated equipment.

The operation of the programmable outputs is controlled by parameters 8A ~ 8F.

4.5 Control Voltage

Control Voltage Terminals



Connect the control supply according to the supply voltage being used:

- 110~120 VAC A1, A2
- 220~240 VAC A2, A3
- 24 VAC/VDC A1, A3

4.6 Power Terminations

The power input and output terminals for EMX4i are at the bottom of the unit.

- Models EMX4i-0024B~EMX4i-0135B use cage clamps.
- Models EMX4i-0184B~EMX4i-0580B use busbars.

NOTE

Some units use aluminium busbars. When connecting power terminations, we recommend cleaning the surface contact area thoroughly (using an emery or stainless steel brush) and using an appropriate jointing compound to prevent corrosion.

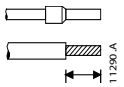
Use only copper stranded or solid conductors, rated for 75 °C or higher.

EMX4i-0024B~EMX4i-0135B

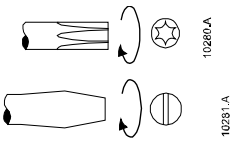
Cable size:

6-70 mm² (AWG 10-2/0)

Torque: 4 Nm (2.9 ft-lb)



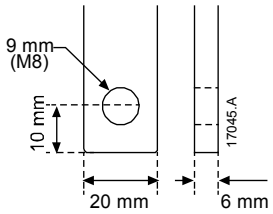
14 mm (0.55 inch)

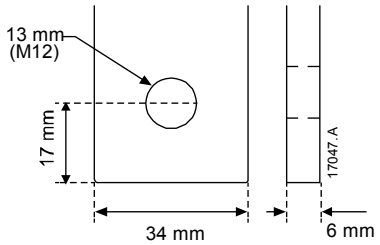


Torx T20 x 150

Flat 7 mm x 150

EMX4i-0184B~EMX4i-0250B	EMX4i-0352B~EMX4i-0580B
19 Nm (14.0 ft-lb)	66 Nm (49.0 ft-lb)





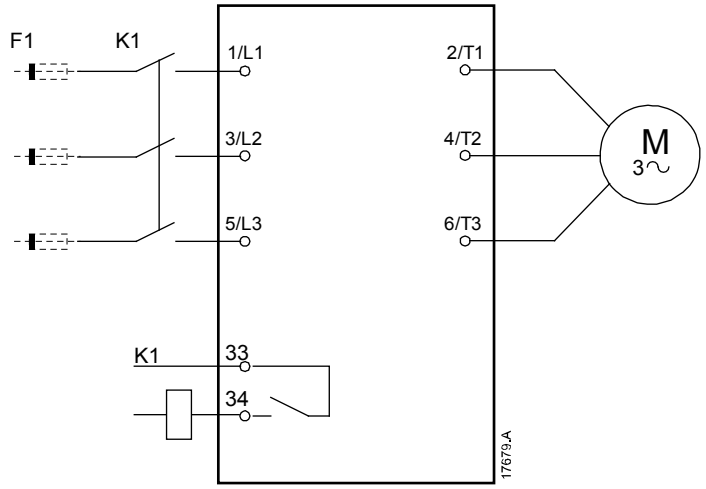
NOTE

If the installation requires large diameter cables, it is possible to complete each termination with two smaller cables, one on each side of the busbar.

Motor Connection

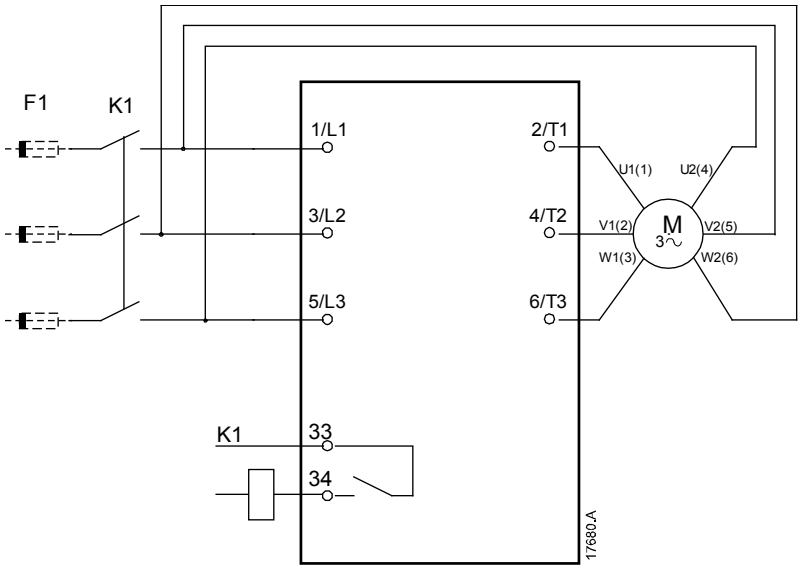
EMX4i soft starters can be connected to the motor in-line or inside delta (also called three-wire and six-wire connection). When connecting in inside delta, enter the motor full load current (FLC) for parameter 1B. The EMX4i will automatically detect whether the motor is connected in-line or inside delta and will calculate the correct inside delta current level.

- **In-line installation**



K1	Main contactor (strongly recommended)
F1	Fuses or circuit breaker (optional)
33, 34	Main contactor output

- **Inside delta installation**

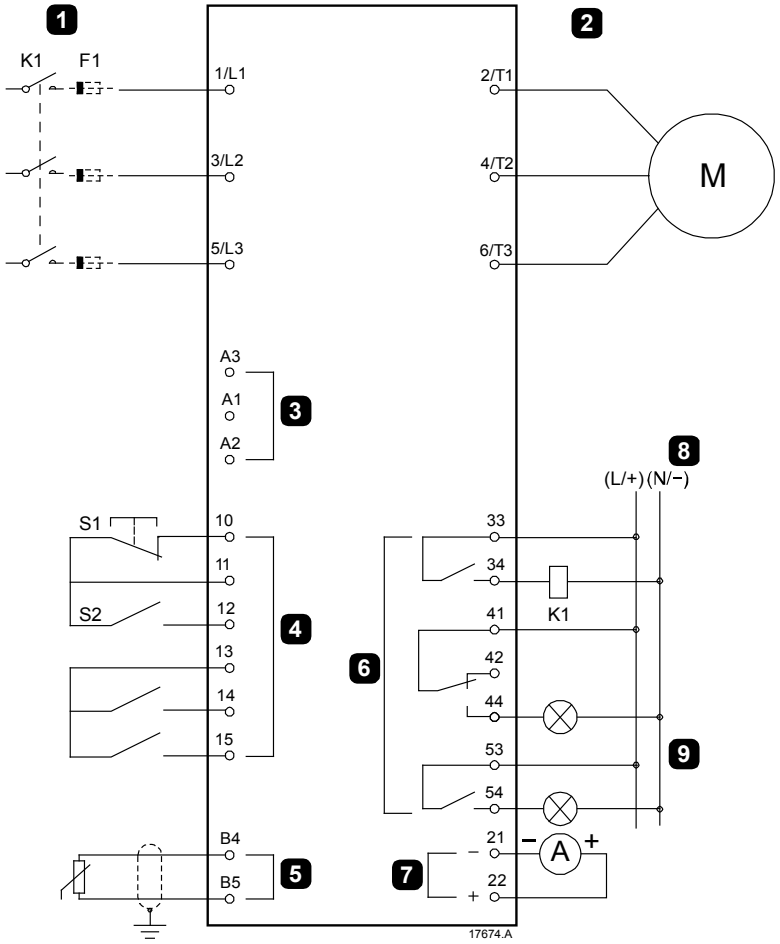


K1	Main contactor
F1	Fuses or circuit breaker (optional)
33, 34	Main contactor output

4.7 Typical Installation

The EMX4i is installed with a main contactor (AC3 rated). Control voltage must be supplied from the input side of the contactor.

The main contactor is controlled by the main contactor output (33, 34).



1	Three-phase supply	10, 11 (S1)	Reset
2	Motor	11, 12 (S2)	Start/Stop
3	Control voltage (soft starter)	13, 14	Programmable input A (default = Input Trip (N/O))
4	Digital inputs		
5	Motor thermistor input	13, 15	Programmable input B (default = Input Trip (N/O))
6	Relay outputs		
7	Analog output	B4, B5	Motor thermistor input
8	Control voltage (external equipment)	33, 34	Main contactor output
9	Pilot lamps	41, 42, 44	Relay output A (default = Run)
K1	Main contactor	53, 54	Relay output B (default = Trip)
F1	Semiconductor fuses (optional)	21, 22	Analog output

4.8 Quick Setup

The Quick Setup Menu makes it easy to configure the EMX4i for common applications. The EMX4i guides you through the most common installation parameters, and suggests a typical setting for the application. You can adjust each parameter to suit your exact requirements.

All other parameters remain at default values. To change other parameter values or review the default settings, use the menu (refer to *Parameter List* for details).

Always set parameter 1B *Motor Full Load Current* to match the motor's nameplate full load current.

Application	*Start Mode*	*Start Ramp Time* (seconds)	*Initial Current* (%)	*Current Limit* (%)	*Adaptive Start Profile*	*Stop Mode*	*Stop Time* (seconds)	*Adaptive Stop Profile*
Pump Centrifugal	Adaptive Control	10	200	500	Early accel.	Adaptive Control	15	Late decel.
Pump bore	Adaptive Control	3	200	500	Early accel.	Adaptive Control	3	Late decel.
Pump Hydraulic	Constant Current	2	200	350	n/a	Coast To Stop	n/a	n/a
Fan Damped	Constant Current	2	200	350	n/a	Coast To Stop	n/a	n/a
Fan Undamped	Constant Current	2	200	450	n/a	Coast To Stop	n/a	n/a
Compressor Screw	Constant Current	2	200	400	n/a	Coast To Stop	n/a	n/a
Compressor Recip	Constant Current	2	200	450	n/a	Coast To Stop	n/a	n/a
Conveyor	Constant Current	5	200	450	n/a	Coast To Stop	n/a	n/a
Bow thruster	Constant Current	5	100	400	n/a	Coast To Stop	n/a	n/a
Bandsaw	Constant Current	2	200	450	n/a	Coast To Stop	n/a	n/a

NOTE

The Adaptive Start and Stop Profile settings only apply when using Adaptive Control. The settings are ignored for all other start and stop modes.

5. Setup Tools

Setup Tools includes options to load or save parameters to a backup file, set the starter's network address, check the status of the inputs and outputs, reset the thermal models or test operation using the Run Simulation.

To access the Setup Tools, press MENU to open the Menu then select Setup Tools.

5.1 Set Date and Time

To set the date and time:

1. Press MENU to open the menu then select Setup Tools.
2. Scroll to Set Date & Time.
3. Press the ▶ button to enter edit mode.
4. Press the ▶ and ◀ buttons to select which part of the date or time to edit.
5. Use the ▲ and ▼ buttons to change the value.
6. Press ▶ after the last digit to save the setting. When the action has been completed, the screen will briefly display a confirmation message, then return to the previous menu level.

5.2 Command Source

The EMX4i can be started and stopped via the digital inputs, remote keypad, communication network, smart card or scheduled auto-start/stop. The command source can be set via the Setup Tools, or using parameter 1A *Command Source*.

If the remote keypad is installed, the LCL/RMT button provides shortcut access to the Command Source function in Setup Tools.

5.3 Commissioning

Commissioning lets the starter be started and stopped via the local keypad. Use the ▲ and ▼ buttons to select a function, then press ▶ to send the selected command to the starter. The available functions are:

- Stop
- Start
- Quick stop (coast to stop)/Reset

5.4 Run Simulation

The run simulation simulates a motor starting, running and stopping to confirm that the soft starter and associated equipment have been installed correctly.

NOTE
The soft starter must be disconnected from mains voltage.
The simulation is only available when the soft starter is in Ready state.

To use the run simulation:

1. Press MENU to open the menu then select Setup Tools.
2. Scroll to Run Simulation and press ▶.

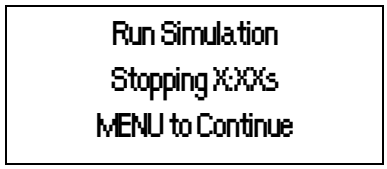
3. Apply a start command from the selected command source. The EMX4i simulates its pre-start checks and closes the main contactor relay. The Run LED flashes.

NOTE
If mains voltage is connected, an error message is shown.

4. Press ▶. The EMX4i simulates starting. The Run LED flashes.

5. Press ▶. The EMX4i simulates running.

6. Apply a stop command from the selected command source. The EMX4i simulates stopping. The Run LED flashes.



7. Press ▶. The Ready LED flashes and the main contactor relay opens.

8. Press ▶. The EMX4i activates then deactivates each programmable output.

9. Press ▶ to return to the Setup Tools.

5.5 Load/Save Settings

Load/Save Settings allows users to:

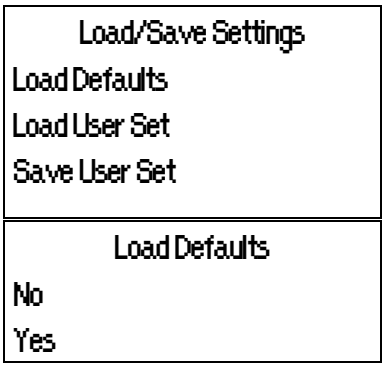
- Reset the EMX4i's parameters to default values
- Load parameter settings from an internal file
- Save the current parameter settings to an internal file

The internal file contains default values until a user file is saved.

To load or save parameter settings:

1. Press MENU to open the menu then select Setup Tools.
2. Scroll to Load/Save Settings and press the ▶ button.
3. Scroll to the required function and press the ▶ button.
4. At the confirmation prompt, select YES to confirm or NO to cancel, then press ▶ to proceed.

   When the action has been completed, the screen will briefly display a confirmation message, then return to the previous menu level.



5.6 USB Save & Load

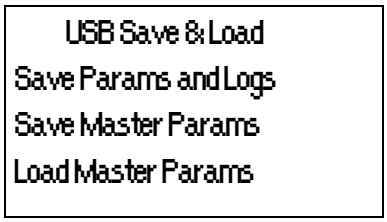
The USB Save & Load menu lets you:

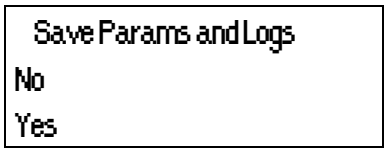
- Save parameter settings and all event log entries to an external file (CSV format)
- Save parameter settings to an external file (proprietary format)
- Load parameter settings from a previously saved external file
- Load custom messages to display on the keypad when a programmable input is active

Save & Load Procedure

1. Connect the external drive to the USB port.
2. Press MENU to open the menu then select Setup Tools.
3. Scroll to USB Save & Load and press the ▶ button.
4. Scroll to the required function and press the ▶ button.
5. At the confirmation prompt, select YES to confirm or NO to cancel, then press ▶ to proceed.

   When the action has been completed, the screen will return to the previous menu level.





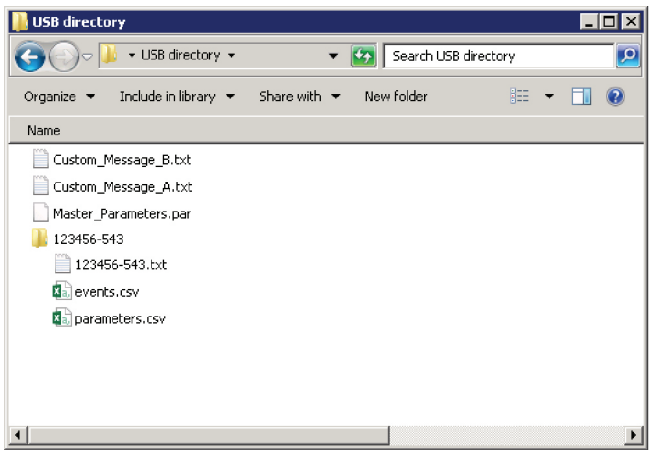
File Locations and Formats

Save Parameters and Logs: The EMX4i will create a directory at the top level of the USB drive, named with the soft starter's serial number. The event log and parameter settings are saved as individual CSV files, and the soft starter's software and system information are saved to a text file.

Save Master Parameters: The EMX4i will create a file called Master_Parameters.par, in the top level of the USB drive.

Load Master Parameters: The EMX4i will load the file Master_Parameters.par from the top level of the USB drive. This file can be created or edited using WinMaster management software.

Load Custom Message: The EMX4i will load the files Custom_Message_A.txt and Custom_Message_B.txt from the top level of the USB drive.



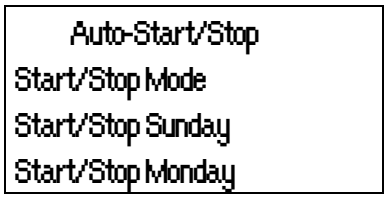
5.7 Auto-Start/Stop

The EMX4i can be configured to automatically start and/or stop the motor once per day. For auto-start/stop to operate:

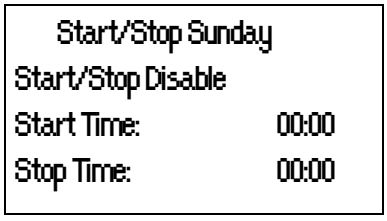
- parameter 4A *Auto-Start/Stop Mode* must be set to 'Enable'
- parameter 1A *Command Source* must be set to 'Clock'
- the reset input must be closed
- the start input (11, 12) must be active. This allows the EMX4i to be stopped via the digital inputs in an emergency.
- parameters 4B ~ 4V: Set as required.

The Auto-Start/Stop option in Setup Tools gives quick access to the auto-start/stop parameters.

1. Press MENU to open the menu then select Setup Tools.
2. Scroll to Auto-Start/Stop and press the ▶ button.
3. Scroll to the required function and press the ▶ button.



4. Adjust the settings as required:
   Press the ▶ and ◀ buttons to select which information to edit.
   Use the ▲ and▼ buttons to change the value.



5. To save changes, press the ▶ button. The EMX4i will confirm the changes.
   To cancel changes, press the ◀ button.

5.8 Network Address

To use the EMX4i on an Ethernet network, separate addresses must be configured for:

- IP Address
- Gateway Address
- Subnet Mask

To set the network addresses:

1. Press MENU to open the menu then select Setup Tools.
2. Scroll to Network Address and press the ▶ button.
3. Scroll to the required function and press the ▶ button.
4. The first digit of the address will be highlighted.
5. Use ◀ and ▶ to select which digit to alter. Use ▲ and ▼ to change the value.
6. Press ▶ after the last digit to save the setting.

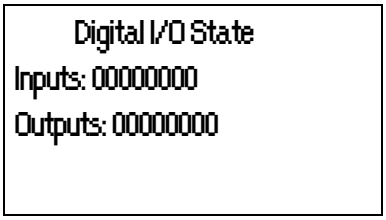
When the action has been completed, the screen will briefly display a confirmation message, then return to the previous menu level.

NOTE
The network address can also be set using parameters 11H~11S.

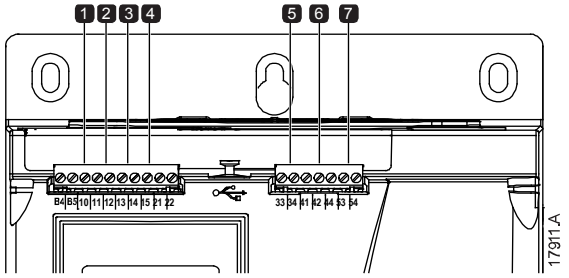
NOTE
To configure the EMX4i for use with other communication protocols, use parameters 11A~11G.

5.9 Digital I/O State

The top line of the screen shows the start/stop, reset and programmable inputs.
The bottom line of the screen shows the fixed Main Contactor output, then programmable outputs A and B.



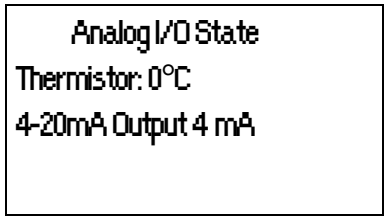
If a smart card is installed, the top line will also show the status of the smart card digital inputs (refer to the smart card instruction for details).



1	10, 11: Reset input
2	11, 12: Start/stop input
3	13, 14: Programmable input A
4	13, 15: Programmable input B
5	33, 34: Main contactor output
6	41, 42, 44: Relay output A
7	53, 54: Relay output B

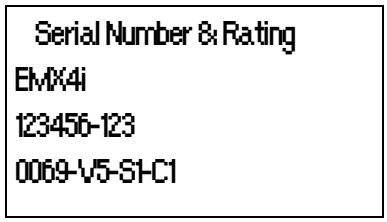
5.10 Analog I/O State

The top line of the screen shows the state of the motor thermistor input.
The bottom line of the screen shows the value of the analog output.



5.11 Serial Number & Rating

The top line of the screen shows the product name.
The middle line shows the unit's serial number.
The bottom line of the screen shows the model number.



5.12 Software Versions

The software versions screen reports the version of each software component in the starter:

- user interface
- motor control
- remote keypad (if connected)
- parameter list
- bootloader

NOTE

Updated software, including alternative languages, can be loaded into the starter via the USB port if required. Contact your local supplier for further information.

5.13 Thermistor Reset

The thermistor input is disabled by default, but activates automatically when a thermistor is detected. If thermistors have previously been connected to the EMX4i but are no longer required, use the Thermistor Reset function to disable the thermistor.

5.14 Reset Thermal Model

The EMX4i's advanced thermal modelling software constantly monitors the motor's performance. This allows the EMX4i to calculate the motor's temperature and ability to start successfully at any time.

The thermal model can be reset if required.

CAUTION

Resetting the motor thermal model will compromise thermal model protection and may compromise motor life. Only reset the thermal model in an emergency.

6. Logs

The Logs Menu provides information on events, trips and starter performance.

To access the Logs Menu on the local keypad, press MENU to open the Menu then select Logs. On the remote keypad, press LOGS.

6.1 Event Log

The Event Log stores details of the starter's most recent trips, warnings, and operations (including starts, stops and configuration changes).

Event 1 is the most recent and event 384 is the oldest stored event.

NOTE

The event log can be exported to an external file for analysis away from the starter. Refer to *USB Save & Load* on page 29 for details.

6.2 Counters

The counters store statistics on the starter's operation:

- Hours run (lifetime and since counter last reset)
- Number of starts (lifetime and since counter last reset)
- Number of times the thermal model has been reset

To view the counters:

1. Open the Logs Menu.
2. Scroll to counters and press ▶.
3. Use the ▲ and▼ buttons to scroll through the counters. Press ▶ to view details.
4. To reset a counter, press ▶ then use the ▲ and▼ buttons to select Reset/Do Not Reset. Press STORE to confirm the action.

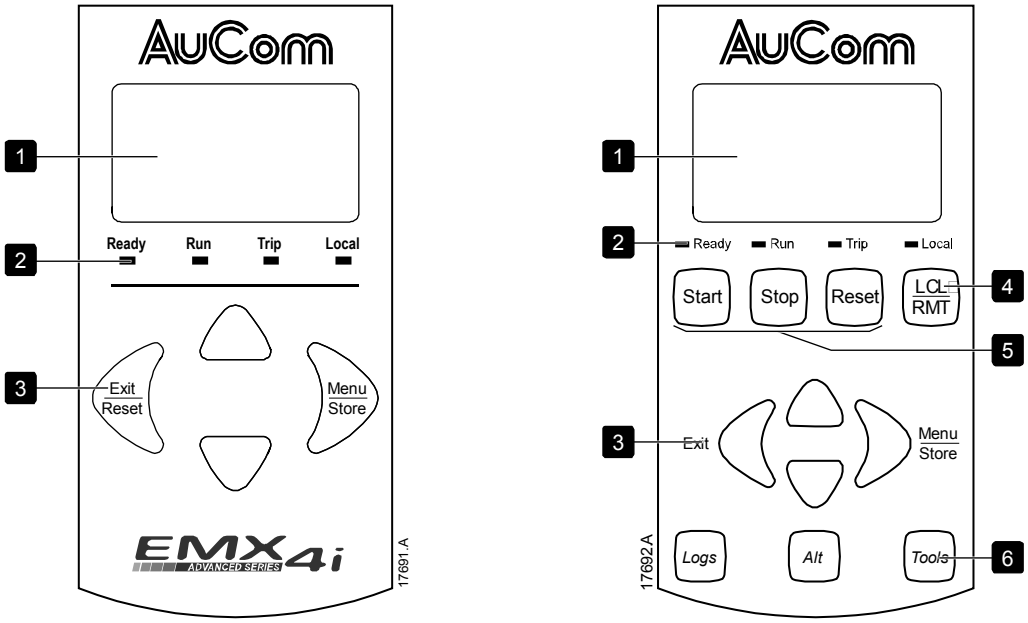
To close the counter and return to the Logs Menu, press ▶.

7. Keypad and Feedback

7.1 The Keypad

The Keypad

Local keypad	Remote keypad (if installed)



1	Four-line display for status and programming details.
2	Status LEDs.
3	Menu navigation buttons: ◀: Exit the menu or parameter, or cancel a parameter change. ▶: Enter a menu or parameter, or save a parameter change. ▲ ▼: Scroll to the next or previous menu or parameter, change the setting of the current parameter or scroll through the status screens.
4	Shortcut to the command source menu in Setup Tools.
5	Soft starter local control buttons
6	Shortcut buttons for quick access to common tasks. LOGS: Open the Logs Menu. ALT: Select which graph to view, or pause/restart the graph (hold longer than 0.5 seconds) TOOLS: Open the Setup Tools.

7.2 Remote Keypad

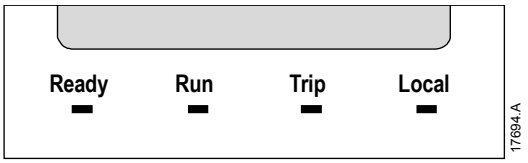
The remote keypad can be used to control the soft starter if parameter 1A *Command Source* is set to 'Remote Keypad'.

- If the remote keypad is not selected as the command source, the START, STOP and RESET buttons will have no effect.
- The menu navigation buttons and display on the remote keypad are always active.
- If a button is pressed on the starter's local keypad, the display on the remote keypad will update to match.

NOTE
The remote keypad can be safely connected or removed while the starter is running. It is not necessary to remove mains or control voltage.

NOTE
If parameter 1A *Command Source* is set to Remote Keypad, removing the remote keypad will cause a trip.

7.3 Starter status LEDs



LED name	On	Flashing
Ready	The motor is stopped and the starter is ready to start.	The motor is stopped and the starter is not ready to start: • waiting for the *Restart Delay* (parameter 5H) • the thermal models indicate the starter and/or motor are too hot to start safely • the reset input (10, 11) is open
Run	The motor is in run state (receiving full voltage).	The motor is starting or stopping.
Trip	The starter has tripped.	The starter is in warning state.
Local	The starter is being controlled via a remote keypad.	–

If all LEDs are off, the starter is not receiving control voltage.

7.4 Displays

The keypad displays a wide range of performance information about the soft starter. To scroll through the feedback screens, press the ▲ and ▼ buttons.

Starter information

At power-up, the starter information screen shows details of the starter's rating, software versions and serial number.

Software versions: user interface, motor control, remote keypad
Model code: current rating, mains voltage, frame size, control voltage
(remote keypad software version is only displayed when a remote keypad is connected)

Starter Status

The starter status screen shows details of the starter's operating status, and real-time performance information as selected in parameters 10H *User Parameter 1* and 10I *User Parameter 2*.

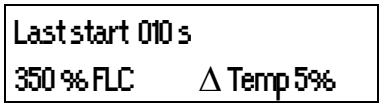
Current

The current screen shows real-time line current on each phase.

Last Start Information

The last start information screen shows details of the most recent successful start:

- start duration (seconds)
- maximum start current drawn (as a percentage of motor full load current)
- calculated rise in motor temperature



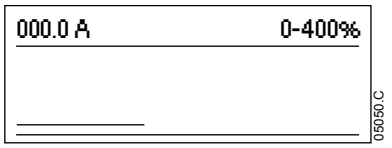
Date and Time

The date/time screen shows the current system date and time (24 hour format). For details on setting the date and time, refer to *Set Date and Time* on page 27.

Performance Graph

The performance graph provides a real-time display of operating performance. Use parameters 10B~10E to format the graph.

The display on the main keypad shows information for motor current.



If a remote keypad is connected, press ALT to change the graph data. The graph can show:

- motor current
- motor temperature
- motor pf
- analog input data from the smart card (if installed)

8. Operation

8.1 Start, Stop and Reset Commands

The EMX4i can be started and stopped via the digital inputs, remote keypad, communication network, smart card or scheduled auto-start/stop. The command source can be set via the Setup Tools, or using parameter 1A *Command Source*.

- The EMX4i will only accept Start and Reset commands from the designated command source.
- The EMX4i will accept Stop commands from the designated command source, but can be forced to stop by opening the reset input, or by opening the start/stop input during an auto-start/stop cycle.
- The programmable input can also be used to override the selected command source (refer to parameter 7A *Input A Function*).

8.2 Command Override

The programmable input (13, 14) can be used to override the command source, for situations where the normal control mechanism has been lost. Set parameter 7A *Input A Function* to the alternative command source (eg 'Command Override: Keypad').

While the input is active, the starter will only accept commands from the selected override source. To restore control to the command source selected in parameter 1A *Command Source*, reopen the input.

8.3 Scheduled Start/Stop

The EMX4i can be configured to automatically start and/or stop the motor once per day. For auto-start/stop to operate:

- parameter 4A *Auto-Start/Stop Mode* must be set to 'Enable'
- parameter 1A *Command Source* must be set to 'Clock'
- the reset input must be closed
- the start input (11, 12) must be active. This allows the EMX4i to be stopped via the digital inputs in an emergency.
- parameters 4B ~ 4V: Set as required.

8.4 PowerThrough

PowerThrough allows the soft starter to control the motor even if the soft starter is damaged on one phase. The EMX4i will use two phase control techniques to soft start and soft stop the motor. PowerThrough is only available with in-line installations. If the starter is installed inside delta, PowerThrough will not operate.

NOTE

PowerThrough operation does not support adaptive control.

- PowerThrough is only available with in-line installations. If the starter is installed inside delta, PowerThrough will not operate.
- PowerThrough remains active until '3-Phase Control Only' is reselected.

A shorted SCR or a short within the bypass contactor will trip the starter on 'Lx-Tx shorted'. If PowerThrough is enabled, the trip can be reset and subsequent starts will use PowerThrough two-phase control; however not all features will be available. The trip LED will flash and the display will indicate '2 Phase - Damaged SCR'.

CAUTION

PowerThrough uses a two-phase soft start technology and additional care is required when sizing circuit breakers and protection. Contact your local supplier for assistance.

CAUTION

The starter will trip on Lx-Tx Shorted on the first start attempt after control power is applied. PowerThrough will not operate if control power is cycled between starts.

PowerThrough operation does not support Adaptive Control soft starting or soft stopping. In PowerThrough, the EMX4i will automatically select constant current soft starting and timed voltage ramp soft stopping. If PowerThrough is enabled, parameters 2C and 2D must be set appropriately.

8.5 Emergency Mode

Emergency mode allows the EMX4i to run the motor and ignore trip conditions.

Emergency mode is controlled via a programmable input (input A 13, 14 or input B 13, 15) and parameter 7A *Input A Function*/7E *Input B Function* must be set to 'Emergency Mode'. A closed circuit across 13, 14 activates emergency mode. When the EMX4i receives a start command, it will continue to run until a stop command is received, ignoring all trips and warnings.

Emergency mode can be used in conjunction with any command source.

NOTE

Although emergency mode operation satisfies the functionality requirements of Fire Mode, AuCom does not recommend its use in situations that require testing and/or compliance with specific standards as it is not certified.

CAUTION

Continued use of emergency mode is not recommended. Emergency mode may compromise the starter and/or motor life as all protections and trips are disabled.

Using the starter in emergency mode will void the product warranty.

8.6 Auxiliary Trip

An external trip circuit (such as a low pressure alarm switch for a pumping system) can be used to trip the soft starter and stop the motor. The external circuit is connected to a programmable input (input A 13, 14 or input B 13, 15). To control the behaviour of the trip, set the following parameters:

- Parameter 7A *Input A Function*: select 'Input Trip (N/O)'.
- Parameter 7B *Input A Trip*: set as required. For example, 'Run Only' limits the input trip to when the soft starter is running only.
- Parameter 7C *Input A Trip Delay*: sets a delay between the input activating and the soft starter tripping.
- Parameter 7D *Input A Initial Delay*: sets a delay before the soft starter monitors the state of the input, after the start signal. For example, a delay may be required to allow time for pipeline pressure to build up.
- Parameter 7J *Input A Name*: select a name, eg 'Input A Trip' (optional).

8.7 Typical Control Methods

The requirements of an application differ between each installation, but the methods listed below are often a good starting point for common applications.

Application	*Start Mode*	*Start Ramp Time* (seconds)	*Initial Current* (%FLC)	*Current Limit* (%FLC)	*Stop Mode*	*Stop Time* (seconds)
Bow thruster	Constant Current	5	100	400	Coast To Stop	n/a
Centrifuge (Separator)	Constant Current	1	200	450	Coast To Stop	n/a
Chipper	Constant Current	1	200	450	Coast To Stop	n/a
Compressor - reciprocating - loaded	Constant Current	1	200	450	Coast To Stop	n/a
Compressor - reciprocating - unloaded	Constant Current	1	200	400	Coast To Stop	n/a
Compressor - screw - loaded	Constant Current	1	200	400	Coast To Stop	n/a
Compressor - screw - unloaded	Constant Current	1	200	350	Coast To Stop	n/a
Conveyor - horizontal	Constant Current	5	200	400	TVR Soft Stop	10
Conveyor - inclined	Constant Current	2	200	450	Coast To Stop	n/a
Conveyor - vertical (bucket)	Constant Current	2	200	450	Coast To Stop	n/a
Crusher - cone	Constant Current	1	200	350	Coast To Stop	n/a
Crusher - jaw	Constant Current	1	200	450	Coast To Stop	n/a
Crusher - rotary	Constant Current	1	200	400	Coast To Stop	n/a
Debarker	Constant Current	1	200	350	Coast To Stop	n/a
Fan - axial (damped)	Constant Current	1	200	350	Coast To Stop	n/a
Fan - axial (undamped)	Constant Current	1	200	450	Coast To Stop	n/a
Fan - centrifugal (damped)	Constant Current	1	200	350	Coast To Stop	n/a
Fan - centrifugal (undamped)	Constant Current	1	200	450	Coast To Stop	n/a
Fan - high pressure	Constant Current	1	200	450	Coast To Stop	n/a
Mill - ball	Constant Current	1	200	450	Coast To Stop	n/a
Mill - hammer	Constant Current	1	200	450	Coast To Stop	n/a
Pump - bore	Adaptive Control (Early accel.)	3	n/a	500	Adaptive Control (Late decel.)	3
Pump - centrifugal	Adaptive Control (Early accel.)	10	n/a	500	Adaptive Control (Late decel.)	15
Pump - Hydraulic	Constant Current	2	200	350	Coast To Stop	n/a

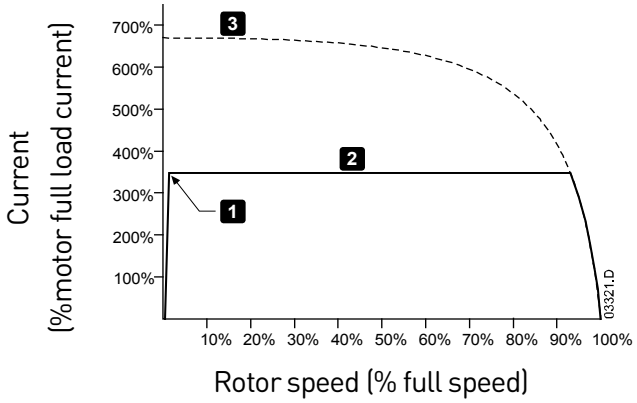
Application	*Start Mode*	*Start Ramp Time* (seconds)	*Initial Current* (%FLC)	*Current Limit* (%FLC)	*Stop Mode*	*Stop Time* (seconds)
Pump - positive displacement	Adaptive Control (Constant accel.)	10	n/a	400	Adaptive Control (Constant decel.)	n/a
Pump - submersible	Adaptive Control (Early accel.)	5	n/a	500	Adaptive Control (Late decel.)	5
Saw - bandsaw (headrig)	Constant Current	1	200	450		n/a
Saw - circular (Slabber, Edger)	Constant Current	1	200	350	Coast To Stop	n/a
Shredder	Constant Current	1	200	450	Coast To Stop	n/a

8.8 Soft Start Methods

Constant Current

Constant current is the traditional form of soft starting, which raises the current from zero to a specified level and keeps the current stable at that level until the motor has accelerated.

Constant current starting is ideal for applications where the start current must be kept below a particular level.



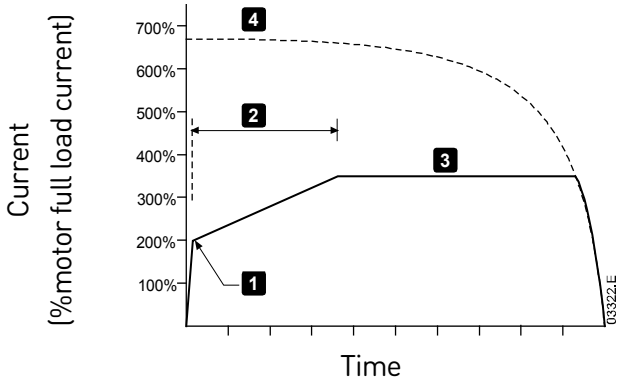
1: *Initial Current* (parameter 2C)
2: *Current Limit* (parameter 2D)
3: Full voltage current

Constant Current with Current Ramp

Current ramp soft starting raises the current from a specified starting level (1) to a maximum limit (3), over an extended period of time (2).

Current ramp starting can be useful for applications where:

- the load can vary between starts (for example a conveyor which may start loaded or unloaded). Set the initial current (parameter 2C) to a level that will start the motor with a light load, and the current limit (parameter 2D) to a level that will start the motor with a heavy load.
- the load breaks away easily, but starting time needs to be extended (for example a centrifugal pump where pipeline pressure needs to build up slowly).
- the electricity supply is limited (for example a generator set), and a slower application of load will allow greater time for the supply to respond.



1: *Initial Current* (parameter 2C)
2: *Start Ramp Time* (parameter 2B)
3: *Current Limit* (parameter 2D)
4: Full voltage current

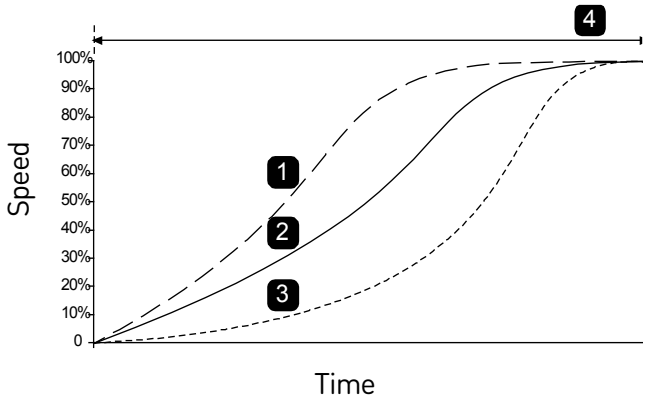
Adaptive Control for Starting

In an adaptive control soft start, the EMX4i adjusts the current in order to start the motor within a specified time and using a selected acceleration profile.

The first Adaptive Control start will use Constant Current. This allows the EMX4i to learn the characteristics of the connected motor. This motor data is used by the EMX4i during subsequent Adaptive Control starts. Set parameter 2D *Current Limit* to an appropriate value.

NOTE

The EMX4i will apply the current limit on all soft starts, including adaptive control. If the current limit is too low or the start ramp time (parameter 2B) is too short, the motor may not start successfully.



Adaptive Start Profile (parameter 2E):

1. Early Acceleration
2. Constant Acceleration
3. Late Acceleration
4. *Start Ramp Time* (parameter 2B)

If replacing a motor connected to an EMX4i programmed for Adaptive Control starting or stopping, the starter will need to learn the characteristics of the new motor. Change the value of parameter 1B *Motor Full Load Current* or parameter 2L *Adaptive Control Gain* to initiate the re-learning process. The next start will use constant current and the next stop will use timed voltage ramp.

- **Fine-tuning Adaptive Control**

If the motor does not start or stop smoothly, adjust the adaptive control gain (parameter 2L). The gain setting determines how much the EMX4i will adjust future adaptive control starts and stops, based on information from the previous start. The gain setting affects both starting and stopping performance.

- If the motor accelerates or decelerates too quickly at the end of a start or stop, increase the gain setting by 5%~10%.
- If the motor speed fluctuates during starting or stopping, decrease the gain setting slightly.

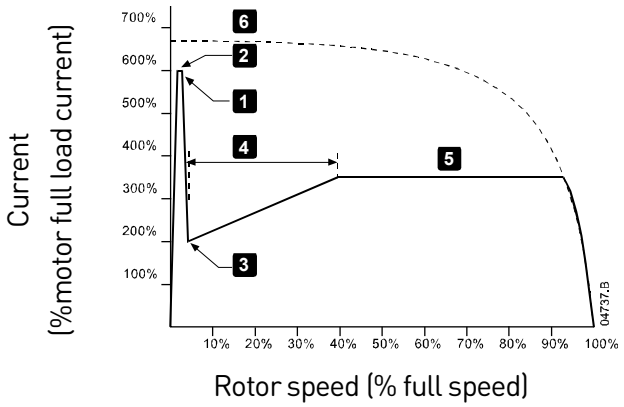
NOTE

Changing the gain setting resets the starter's adaptive control learning. The first start after changing the gain will use constant current.

Constant Current with Kickstart

Kickstart provides a short boost of extra torque at the beginning of a start, and can be used in conjunction with current ramp or constant current starting.

Kickstart can be useful to help start loads that require high breakaway torque but then accelerate easily (for example helical rotor pumps).



1: *Kickstart Level* (parameter 2G)
2: *Kickstart Time* (parameter 2F)
3: *Initial Current* (parameter 2C)
4: *Start Ramp Time* (parameter 2B)
5: *Current Limit* (parameter 2D)
6: Full voltage current

8.9 Stop Methods

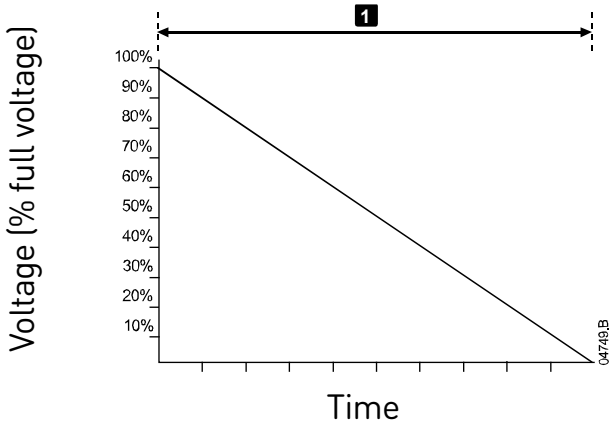
Coast to Stop

Coast to stop lets the motor slow at its natural rate, with no control from the soft starter. The time required to stop will depend on the type of load.

TVR Soft Stop

Timed voltage ramp reduces the voltage to the motor gradually over a defined time. The load may continue to run after the stop ramp is complete.

Timed voltage ramp stopping can be useful for applications where the stop time needs to be extended, or to avoid transients on generator set supplies.



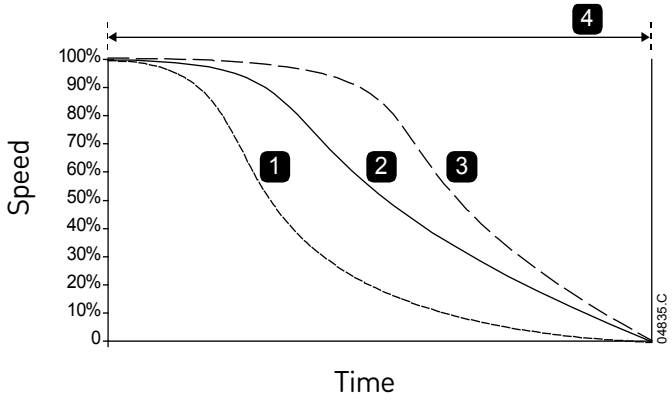
1: *Stop Time* (parameter 2J)

Adaptive Control for Stopping

In an adaptive control soft stop, the EMX4i controls the current in order to stop the motor within a specified time and using a selected deceleration profile. Adaptive Control can be useful in extending the stopping time of low inertia loads.

The first Adaptive Control stop will be a normal soft stop. This allows the EMX4i to learn the characteristics of the connected motor. This motor data is used by the EMX4i during subsequent Adaptive Control stops.

If replacing a motor connected to an EMX4i programmed for Adaptive Control starting or stopping, the starter will need to learn the characteristics of the new motor. Change the value of parameter 1B *Motor Full Load Current* or parameter 2L *Adaptive Control Gain* to initiate the re-learning process. The next start will use constant current and the next stop will use timed voltage ramp.



Adaptive Stop Profile (parameter 2K):

1. Early Deceleration
2. Constant Deceleration
3. Late Deceleration
4. *Stop Time* (parameter 2J)

Adaptive Control is ideal for pumping applications, where it can minimise the damaging effects of fluid hammer. We recommend testing the three profiles to identify the best profile for the application.

Adaptive Stop Profile	Application
Late Deceleration	High head systems where even a small decrease in motor/pump speed results in a rapid transition between forward flow and reverse flow.
Constant Deceleration	Low to medium head, high flow applications where the fluid has high momentum.
Early Deceleration	Open pump systems where fluid must drain back through the pump without driving the pump in reverse.

DC Brake

Brake reduces the time required to stop the motor.

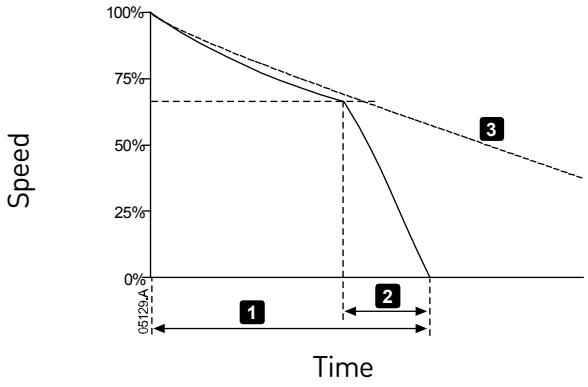
During braking an increased noise level from the motor may be audible. This is a normal part of motor braking.

CAUTION
When using DC brake, the mains supply must be connected to the soft starter (input terminals L1, L2, L3) in positive phase sequence.

CAUTION
If the brake torque is set too high, the motor will stop before the end of the brake time and the motor will suffer unnecessary heating which could result in damage. Careful configuration is required to ensure safe operation of the starter and motor.

A high brake torque setting can result in peak currents up to motor DOL being drawn while the motor is stopping. Ensure protection fuses installed in the motor branch circuit are selected appropriately.

CAUTION
Brake operation causes the motor to heat faster than the rate calculated by the motor thermal model. If you are using brake, install a motor thermistor or allow sufficient restart delay (parameter 5H).



1: *Stop Time* (parameter 2J)
2: *Brake Time* (parameter 2P)
3: Coast to stop time

Parameter settings:

- Parameter 2I *Stop Mode*: set to 'DC Brake'.
- Parameter 2J *Stop Time*: This is the total braking time (1) and must be set sufficiently longer than the brake time (parameter 2P) to allow the pre-braking stage to reduce motor speed to approximately 70%. If the stop time is too short, braking will not be successful and the motor will coast to stop.
- Parameter 2O *DC Brake Torque*: set as required to slow the load. If set too low, the motor will not stop completely and will coast to stop after the end of the braking period.

- Parameter 2P *DC Brake Time*: Set Brake Time (parameter 2P) to approximately one quarter of the programmed Stop Time. This sets the time for the Full Brake stage (2).

DC Brake with External Zero Speed Sensor

For loads which may vary between braking cycles, install an external zero-speed sensor to ensure the soft starter ends DC braking when the motor has reached a standstill. This avoids unnecessary motor heating.

Configure DC brake for the longest braking time required, and also set parameter 7A *Input A Function* to 'Zero Speed Sensor'. When the motor reaches a standstill, the zero speed sensor opens the circuit across 13, 14 and the soft starter terminates the stop.

Soft Brake

For applications with high inertia and/or a variable load requiring the maximum possible braking torque, the EMX4i can be configured for soft braking.

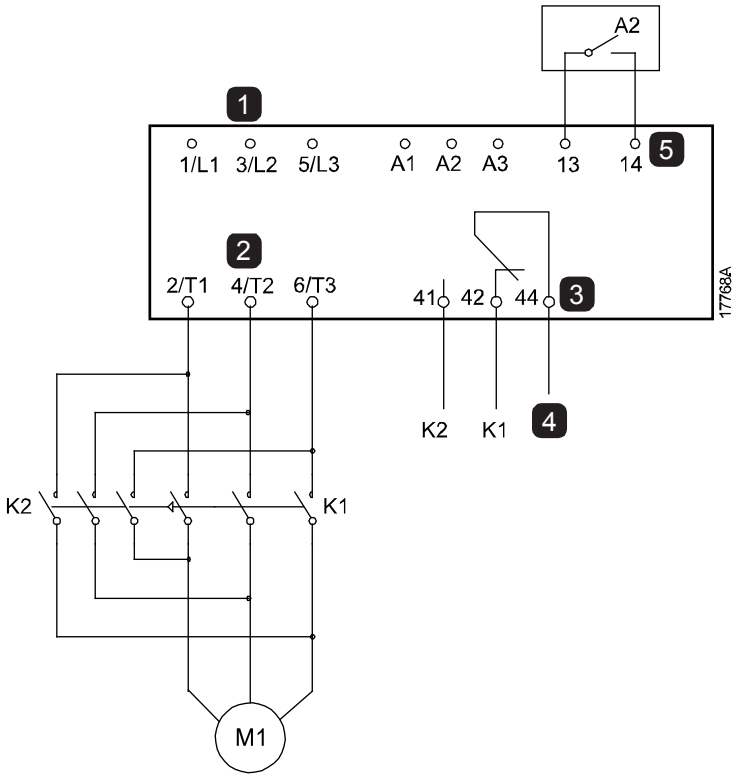
The EMX4i uses a changeover relay to control forward run and braking contactors. While braking, the EMX4i reverses the phase sequence to the motor and supplies reduced current, gently slowing the load.

When motor speed approaches zero, the zero speed sensor (A2) stops the soft starter and opens the braking contactor (K2).

Soft braking can be used with both the primary and secondary motor sets, and must be configured separately for each.

Parameter settings:

- Parameter 2I *Stop Mode*: set to 'Soft Brake'
- Parameter 2Q *Brake Current Limit*: set as required to slow the load
- Parameter 2R *Soft Brake Delay*: controls the time the soft starter will wait after a stop signal is received, before it begins to supply braking current to the motor. Set to allow time for K1 and K2 to switch.
- Parameter 7A *Input A Function*: set to 'Zero Speed Sensor'
- Parameter 8A *Relay A Function*: set to 'Soft Brake Relay'



1	Three-phase supply
2	Motor terminals
3	Relay output A
4	K1/K2 coil supply
5	Programmable input A

K1	Line contactor (Run)
K2	Line contactor (Brake)
A2	Zero speed sensor

8.10 Jog Operation

Jog runs the motor at reduced speed, to allow alignment of the load or to assist servicing. The motor can be jogged in either forward or reverse direction.

Jog operation is controlled by the start/stop input (11, 12), and parameter 1A *Command Source* must be set to 'Digital Input'. To operate in jog, a programmable input must be set to jog (refer to parameter 7A for details) and the input must be closed when the start signal is applied.

CAUTION

Slow speed running is not intended for continuous operation due to reduced motor cooling.

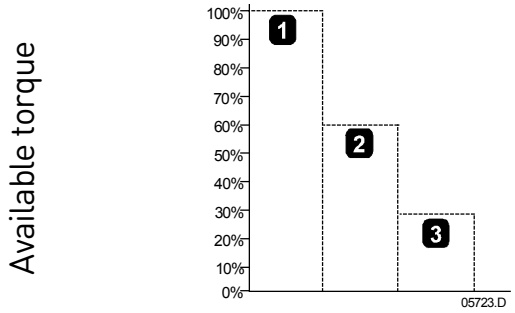
Jog operation causes the motor to heat faster than the rate calculated by the motor thermal model. If you are using jog, install a motor thermistor or allow sufficient restart delay (parameter 5H).

The maximum available torque for jog forward is approximately 50%~75% of motor full load torque (FLT) depending on the motor. The torque when the motor is jogged in reverse is approximately 25% to 50% of FLT.

Parameters 2H and 3H *Jog Torque* control how much of the maximum available jog torque the soft starter will apply to the motor.

NOTE

Torque settings above 50% may cause increased shaft vibration.



1. Motor FLT
2. Jog forward maximum torque
3. Jog reverse maximum torque

8.11 Inside Delta Operation

When connecting in inside delta, enter the motor full load current (FLC) for parameter 1B. The EMX4i will automatically detect whether the motor is connected in-line or inside delta and will calculate the correct inside delta current level.

Adaptive Control, Jog, Brake and PowerThrough functions are not supported with inside delta (six-wire) operation. If these functions are programmed when the starter is connected inside delta the behaviour is as given below:

Adaptive Control Start	The starter performs a constant current start.
Adaptive Control Stop	The starter performs a TVR soft stop if parameter 2J *Stop Time* is >0 secs. If parameter 2J is set to 0 secs the starter performs a coast to stop.
Jog	The starter issues a warning with the error message Unsupported option.
DC Brake	The starter performs a coast to stop.
Soft Brake	The starter performs a coast to stop.
PowerThrough	The starter trips with the error message Lx-Tx Shorted.

NOTE

When connected in inside delta, the EMX4i will not detect phase loss on T2 during run.

8.12 Secondary Motor Set

The EMX4i can be programmed with two separate starting and stopping profiles. This allows the soft starter to control the motor in two different starting and stopping configurations.

This is ideal for situations where the motor may start in two different conditions (such as loaded and unloaded conveyors).

The EMX4i will use the secondary motor settings to control a start when instructed via a programmable input (refer to parameter 7A *Input A Function* and 7E *Input B Function*).

NOTE

EMX4i soft starters are not suitable for controlling two separate motors. The secondary parameter set should only be used for a secondary configuration of the primary motor.

9. Programmable Parameters

9.1 Programming Menu

The Programming Menu lets you view and change programmable parameters that control how the EMX4i operates.

To open the Programming Menu, press the MENU button while viewing the monitoring screens.

9.2 Altering Parameter Values

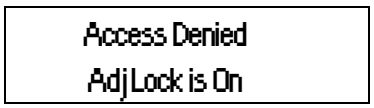
To change a parameter value:

- scroll to the appropriate parameter in the Programming Menu and press ▶ to enter edit mode.
- to alter the parameter setting, use the ▲ and ▼ buttons. Pressing ▲ or ▼ once will increase or decrease the value by one unit. If the button is held for longer than five seconds, the value will increase or decrease at a faster rate.
- to save changes, press STORE. The setting shown on the display will be saved and the keypad will return to the parameter list.
- to cancel changes, press EXIT. The keypad will ask for confirmation, then return to the parameter list without saving changes.

9.3 Adjustment Lock

You can prevent users from altering parameter settings by turning on the adjustment lock (parameter 10G *Adjustment Lock*).

If a user attempts to change a parameter value when the adjustment lock is active, an error message is displayed:



9.4 Parameter List

		Parameter Group	Default Setting
1		Motor Details	
	1A	*Command Source*	Digital Input
	1B	*Motor Full Load Current*	Model dependent
	1C	*Locked Rotor Time*	00:10 (mm:ss)
	1D	*Locked Rotor Current*	600%
	1E	*Motor Service Factor*	105%
2		Motor Start/Stop	
	2A	*Start Mode*	Constant Current
	2B	*Start Ramp Time*	00:10 (mm:ss)
	2C	*Initial Current*	350%
	2D	*Current Limit*	350%
	2E	*Adaptive Start Profile*	Constant Acceleration
	2F	*Kickstart Time*	000 ms
	2G	*Kickstart Level*	500%
	2H	*Jog Torque*	50%
	2I	*Stop Mode*	TVR Soft Stop
	2J	*Stop Time*	00:01 (mm:ss)
	2K	*Adaptive Stop Profile*	Constant Deceleration
	2L	*Adaptive Control Gain*	75%
	2M	*Multi Pump*	Single Pump
	2N	*Start Delay*	00:00 (mm:ss)
	2O	*DC Brake Torque*	20%
	2P	*DC Brake Time*	00:01 (mm:ss)
	2Q	*Brake Current Limit*	250%
	2R	*Soft Brake Delay*	400 ms
3		Motor Start/Stop 2	
	3A	*Start Mode-2*	Constant Current
	3B	*Start Ramp Time-2*	00:10 (mm:ss)
	3C	*Initial Current-2*	350%
	3D	*Current Limit-2*	350%
	3E	*Adaptive Start Profile-2*	Constant Acceleration
	3F	*Kickstart Time-2*	000 ms
	3G	*Kickstart Level-2*	500%

	3H	*Jog Torque-2*	50%
	3I	*Stop Mode-2*	TVR Soft Stop
	3J	*Stop Time-2*	00:01 (mm:ss)
	3K	*Adaptive Stop Profile-2*	Constant Deceleration
	3L	*Adaptive Control Gain-2*	75%
	3M	*Multi Pump-2*	Single Pump
	3N	*Start Delay-2*	00:00 (mm:ss)
	3O	*DC Brake Torque-2*	20%
	3P	*DC Brake Time-2*	00:01 (mm:ss)
	3Q	*Brake Current Limit-2*	250%
	3R	*Soft Brake Delay-2*	400 ms
4		Auto-Start/Stop	
	4A	*Auto-Start/Stop Mode*	Disable
	4B	*Sunday Mode*	Start/Stop Disable
	4C	*Sunday Start Time*	00:00 (hh:mm)
	4D	*Sunday Stop Time*	00:00 (hh:mm)
	4E	*Monday Mode*	Start/Stop Disable
	4F	*Monday Start Time*	00:00 (hh:mm)
	4G	*Monday Stop Time*	00:00 (hh:mm)
	4H	*Tuesday Mode*	Start/Stop Disable
	4I	*Tuesday Start Time*	00:00 (hh:mm)
	4J	*Tuesday Stop Time*	00:00 (hh:mm)
	4K	*Wednesday Mode*	Start/Stop Disable
	4L	*Wednesday Start Time*	00:00 (hh:mm)
	4M	*Wednesday Stop Time*	00:00 (hh:mm)
	4N	*Thursday Mode*	Start/Stop Disable
	4O	*Thursday Start Time*	00:00 (hh:mm)
	4P	*Thursday Stop Time*	00:00 (hh:mm)
	4Q	*Friday Mode*	Start/Stop Disable
	4R	*Friday Start Time*	00:00 (hh:mm)
	4S	*Friday Stop Time*	00:00 (hh:mm)
	4T	*Saturday Mode*	Start/Stop Disable
	4U	*Saturday Start Time*	00:00 (hh:mm)
	4V	*Saturday Stop Time*	00:00 (hh:mm)

5		Protection Levels	
	5A	*Current Imbalance*	30%
	5B	*Current Imbalance Delay*	00:03 (mm:ss)
	5C	*Undercurrent*	20%
	5D	*Undercurrent Delay*	00:05 (mm:ss)
	5E	*Overcurrent*	400%
	5F	*Overcurrent Delay*	00:00 (mm:ss)
	5G	*Excess Start Time*	00:20 (mm:ss)
	5H	*Restart Delay*	00:10 (mm:ss)
6		Protection Actions	
	6A	*Current Imbalance*	Soft Trip and Log
	6B	*Undercurrent*	Soft Trip and Log
	6C	*Overcurrent*	Soft Trip and Log
	6D	*Excess Start Time*	Soft Trip and Log
	6E	*Input A Trip*	Soft Trip and Log
	6F	*Input B Trip*	Soft Trip and Log
	6G	*Network Communications*	Soft Trip and Log
	6H	*Remote Keypad Fault*	Soft Trip and Log
	6I	*Frequency*	Soft Trip and Log
	6J	*Motor Overtemperature*	Soft Trip and Log
	6K	*Motor Thermistor Circuit*	Soft Trip and Log
	6L	*Shorted SCR Action*	3-Phase Control Only
	6M	*Battery/Clock*	Soft Trip and Log
	6N	*Pressure Sensor*	Soft Trip and Log
	6O	*Flow Sensor*	Soft Trip and Log
	6P	*Depth Sensor*	Soft Trip and Log
	6Q	*High Pressure*	Soft Trip and Log
	6R	*Low Pressure*	Soft Trip and Log
	6S	*High Flow*	Soft Trip and Log
	6T	*Low Flow*	Soft Trip and Log
	6U	*Flow Switch*	Soft Trip and Log
	6V	*Well Depth*	Soft Trip and Log
7		Inputs	
	7A	*Input A Function*	Input Trip (N/O)
	7B	*Input A Trip*	Operating Only
	7C	*Input A Trip Delay*	00:00 (mm:ss)

	7D	*Input A Initial Delay*	00:00 (mm:ss)
	7E	*Input B Function*	Input Trip (N/O)
	7F	*Input B Trip*	Operating Only
	7G	*Input B Trip Delay*	00:00 (mm:ss)
	7H	*Input B Initial Delay*	00:00 (mm:ss)
	7I	*Reset/Enable Logic*	Normally Closed (N/C)
	7J	*Input A Name*	Input A Trip
	7K	*Input B Name*	Input B Trip
8		Relay Outputs	
	8A	*Relay A Function*	Run
	8B	*Relay A On Delay*	00:00 (mm:ss)
	8C	*Relay A Off Delay*	00:00 (mm:ss)
	8D	*Relay B Function*	Run
	8E	*Relay B On Delay*	00:00 (mm:ss)
	8F	*Relay B Off Delay*	00:00 (mm:ss)
	8G	*Low Current Flag*	50%
	8H	*High Current Flag*	100%
	8I	*Motor Temperature Flag*	80%
	8J	*Main Contactor Time*	400 ms
9		Analog Output	
	9A	*Analog Output A*	Current (% FLC)
	9B	*Analog A Scale*	4-20 mA
	9C	*Analog A Maximum Adjustment*	100%
	9D	*Analog A Minimum Adjustment*	000%
10		Display	
	10A	*Language*	English
	10B	*Temperature Scale*	Celsius
	10C	*Graph Timebase*	30 seconds
	10D	*Graph Maximum Adjustment*	400%
	10E	*Graph Minimum Adjustment*	0%
	10F	*Current Calibration*	100%
	10G	*Adjustment Lock*	Read & Write
	10H	*User Parameter 1*	Blank
	10I	*User Parameter 2*	Blank
11		Communications Adapter	
	11A	*Modbus Address*	1

	11B	*Modbus Baud Rate*	9600
	11C	*Modbus Parity*	None
	11D	*Modbus Timeout*	Off
	11E	*Devicenet Address*	0
	11F	*Devicenet Baud Rate*	125kB
	11G	*Profibus Address*	1
	11H	*Gateway Address*	192
	11I	*Gateway Address* 2	168
	11J	*Gateway Address* 3	0
	11K	*Gateway Address* 4	100
	11L	*IP Address*	192
	11M	*IP Address* 2	168
	11N	*IP Address* 3	0
	11O	*IP Address* 4	2
	11P	*Subnet Mask*	255
	11Q	*Subnet Mask* 2	255
	11R	*Subnet Mask* 3	255
	11S	*Subnet Mask* 4	0
	11T	*DHCP*	Disable
	11U	*Location ID*	0
12		Pump Input Configuration	
	12A	*Auto-Reset Count*	0
	12B	*Auto-Reset Delay*	00:05 (mm:ss)
	12C	*Pressure Sensor Type*	None
	12D	*Pressure Units*	kPa
	12E	*Pressure at 4 mA*	0
	12F	*Pressure at 20 mA*	0
	12G	*Flow Sensor Type*	None
	12H	*Flow Units*	litres/second
	12I	*Flow at 4 mA*	0
	12J	*Flow at 20 mA*	0
	12K	*Units per Minute at Max Flow*	0
	12L	*Pulses per Minute at Max Flow*	0
	12M	*Units per Pulse*	0
	12N	*Depth Sensor Type*	None
	12O	*Depth Units*	metres

	12P	*Depth at 4 mA*	0
	12Q	*Depth at 20 mA*	0
13		Flow Protection	
	13A	*High Flow Trip Level*	0
	13B	*Low Flow Trip Level*	15
	13C	*Flow Start Delay*	00:00:05 (mm:ss:ms)
	13D	*Flow Response Delay*	00:01:00 (mm:ss:ms)
14		Pressure Protection	
	14A	*High Pressure Trip Level*	0
	14B	*High Pressure Start Delay*	00:00:15 (mm:ss:ms)
	14C	*High Pressure Response Delay*	00:00:01 (mm:ss:ms)
	14D	*Low Pressure Trip Level*	100
	14E	*Low Pressure Start Delay*	00:00:15 (mm:ss:ms)
	14F	*Low Pressure Response Delay*	00:00:01 (mm:ss:ms)
15		Pressure Control	
	15A	*Pressure Control Mode*	Off
	15B	*Start Pressure Level*	15
	15C	*Start Response Delay*	00:00:15 (mm:ss:ms)
	15D	*Stop Pressure Level*	100
	15E	*Stop Response Delay*	00:00:15 (mm:ss:ms)
16		Depth Protection	
	16A	*Depth Trip Level*	100
	16B	*Depth Reset Level*	100
	16C	*Depth Start Delay*	00:00:01 (mm:ss:ms)
	16D	*Depth Response Delay*	00:00:01 (mm:ss:ms)
17		Thermal Protection	
	17A	*Temperature Sensor Type*	None
	17B	*Temperature Trip Level*	30
20		Advanced	
	20A	*Tracking Gain*	50%
	20B	*Pedestal Detect*	80%
	20C	*Bypass Contactor Delay*	150 ms
	20D	*Current Rating*	0020
	20E	*Screen Timeout*	1 minute

9.5 1 Motor Details

1A – *Command Source*

Options:	Digital Input (default)	The EMX4i will accept start and stop commands from the digital inputs.
	Network	The EMX4i will accept start and stop commands from the communication expansion card.
	Remote Keypad	The EMX4i will accept start and stop commands from the Remote Keypad.
	Clock	The EMX4i will start and stop as scheduled in parameters 4A to 4V.
	Smart Card	The EMX4i will accept start and stop commands from the smart card.
	Smart Card & Clock	The EMX4i will accept start commands from the smart card if they are within the operating schedule set in parameters 4A to 4V. A stop command from the smart card will be accepted regardless of the schedule.

Description: Selects the command source for controlling the soft starter.

1B – *Motor Full Load Current*

Range: Model dependent

Description: Matches the starter to the connected motor's full load current. Set to the full load current (FLC) rating shown on the motor nameplate.

1C – *Locked Rotor Time*

Range: 0:01 - 2:00 (minutes:seconds) **Default:** 10 seconds

Description: Sets the maximum length of time the motor can sustain locked rotor current from cold before reaching its maximum temperature. Set according to the motor datasheet.

1D – *Locked Rotor Current*

Range: 400% - 1200% FLC **Default:** 600%

Description: Sets the locked rotor current of the connected motor, as a percentage of full load current. Set according to the motor datasheet.

1E – *Motor Service Factor*

Range: 100% - 130% **Default:** 105%

Description: Sets the motor service factor used by the thermal model. If the motor runs at full load current, it will reach 100%. Set according to the motor datasheet.

9.6 2 Motor Start/Stop

2A – *Start Mode*

Options: Constant Current (default)
Adaptive Control

Description: Selects the soft start mode.

2B – *Start Ramp Time*

Range: 0:01 - 3:00 (minutes:seconds) **Default:** 10 seconds

Description: Sets the total start time for an Adaptive Control start or the ramp time for current ramp starting (from the initial current to the current limit).

2C – *Initial Current*

Range: 100% - 600% FLC **Default:** 350%

Description: Sets the initial start current level for current ramp starting, as a percentage of motor full load current. Set so that the motor begins to accelerate immediately after a start is initiated.
If current ramp starting is not required, set the initial current equal to the current limit.

2D – *Current Limit*

Range: 100% - 600% FLC **Default:** 350%

Description: Sets the current limit for constant current and current ramp soft starting, as a percentage of motor full load current.

NOTE
The EMX4i will apply the current limit on all soft starts, including adaptive control. If the current limit is too low or the start ramp time (parameter 2B) is too short, the motor may not start successfully.

2E – *Adaptive Start Profile*

Options: Early Acceleration
Constant Acceleration (default)
Late Acceleration

Description: Selects which profile the EMX4i will use for an Adaptive Control soft start.

2F – *Kickstart Time*

Range: 0 – 2000 milliseconds **Default:** 0000 milliseconds

Description: Sets the kickstart duration. A setting of 0 disables kickstart.

2G – *Kickstart Level*

Range: 100% - 700% FLC **Default:** 500%

Description: Sets the level of the kickstart current.

CAUTION
Kickstart subjects the mechanical equipment to increased torque levels. Ensure the motor, load and couplings can handle the additional torque before using this feature.

2H – *Jog Torque*

The EMX4i can jog the motor at a reduced speed, which allows precise positioning of belts and flywheels. Jog can be used for either forward or reverse operation.

Range: 20% - 100% **Default:** 50%

Description: Sets the current limit for jog operation.

2I – *Stop Mode*

Options: Coast To Stop
TVR Soft Stop (default)
Adaptive Control
DC Brake
Soft Brake

Description: Selects the stop mode.

2J – *Stop Time*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 1 second

Description: Sets the time for soft stopping the motor using timed voltage ramp or Adaptive Control.
If a main contactor is installed, the contactor must remain closed until the end of the stop time. Use the main contactor output (33, 34) to control the main contactor.

2K – *Adaptive Stop Profile*

Options: Early Deceleration
Constant Deceleration (default)
Late Deceleration

Description: Selects which profile the EMX4i will use for an Adaptive Control soft stop.

2L – *Adaptive Control Gain*

Range: 1% - 200% **Default:** 75%

Description: Adjusts the performance of Adaptive Control. This setting affects both starting and stopping control.

2M – *Multi Pump*

Options: Single Pump (default)
Manifold Pump

Description: Adjusts the performance of adaptive control to suit installations with multiple pumps connected to a common outlet manifold.

2N – *Start Delay*

Range: 0:00 - 3:20 (minutes:seconds) **Default:** 0 second

Description: Sets a delay after the starter receives a start command, before it starts the motor.

2O – *DC Brake Torque*

Range: 20% - 100% **Default:** 20%

Description: Sets the amount of brake torque the EMX4i will use to slow the motor.

2P – *DC Brake Time*

Range: 0:01 - 0:30 (minutes:seconds) **Default:** 1 second

Description: Sets the duration for DC injection during a braking stop.

2Q – *Brake Current Limit*

Range: 100% - 600% FLC **Default:** 250%

Description: Sets the current limit for soft brake.

2R – *Soft Brake Delay*

Range: 400 - 2000 (milliseconds) **Default:** 400 milliseconds

Description: Sets the time the soft starter will wait after a stop signal is received, before it begins to supply braking current to the motor. Set to allow time for K1 and K2 to switch.

9.7 3 Motor Start/Stop-2

The parameters in this group control the operation of the secondary configuration of the motor. Use the programmable input to select the active motor set.

To use the secondary motor data, parameter 7A must be set to 'Motor Set Select' and the input must be closed when a start command is given. The EMX4i checks which motor data to use at a start, and will use that motor data for the entire start/stop cycle.

NOTE

EMX4i soft starters are not suitable for controlling two separate motors. The secondary parameter set should only be used for a secondary configuration of the primary motor.

3A – *Start Mode-2*

Options: Constant Current (default)
Adaptive Control

Description: Selects the soft start mode.

3B – *Start Ramp Time-2*

Range: 0:01 - 3:00 (minutes:seconds) **Default:** 10 seconds

Description: Sets the total start time for an Adaptive Control start or the ramp time for current ramp starting (from the initial current to the current limit).

3C – *Initial Current-2*

Range: 100% - 600% FLC **Default:** 350%

Description: Sets the initial start current level for current ramp starting, as a percentage of motor full load current. Set so that the motor begins to accelerate immediately after a start is initiated.
If current ramp starting is not required, set the initial current equal to the current limit.

3D – *Current Limit-2*

Range: 100% - 600% FLC **Default:** 350%

Description: Sets the current limit for constant current and current ramp soft starting, as a percentage of motor full load current.

NOTE

The EMX4i will apply the current limit on all soft starts, including adaptive control. If the current limit is too low or the start ramp time (parameter 2B) is too short, the motor may not start successfully.

3E – *Adaptive Start Profile-2*

Options: Early Acceleration
Constant Acceleration (default)
Late Acceleration

Description: Selects which profile the EMX4i will use for an Adaptive Control soft start.

3F – *Kickstart Time-2*

Range: 0 – 2000 milliseconds **Default:** 0000 milliseconds

Description: Sets the kickstart duration. A setting of 0 disables kickstart.

3G – *Kickstart Level-2*

Range: 100% - 700% FLC **Default:** 500%

Description: Sets the level of the kickstart current.

3H – *Jog Torque-2*

Range: 20% - 100% **Default:** 50%

Description: Sets the current limit for jog operation.

3I – *Stop Mode-2*

Options: Coast To Stop
TVR Soft Stop (default)
Adaptive Control
DC Brake
Soft Brake

Description: Selects the stop mode.

3J – *Stop Time-2*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 1 second

Description: Sets the time for soft stopping the motor using timed voltage ramp or Adaptive Control.
If a main contactor is installed, the contactor must remain closed until the end of the stop time. Use the main contactor output (33, 34) to control the main contactor.

3K – *Adaptive Stop Profile-2*

Options: Early Deceleration
Constant Deceleration (default)
Late Deceleration

Description: Selects which profile the EMX4i will use for an Adaptive Control soft stop.

3L – *Adaptive Control Gain-2*

Range: 1%~200% **Default:** 75%

Description: Adjusts the performance of Adaptive Control. This setting affects both starting and stopping control.

3M – *Multi Pump-2*

Options: Single Pump (default)
Manifold Pump

Description: Adjusts the performance of adaptive control to suit installations with multiple pumps connected to a common outlet manifold.

3N – *Start Delay-2*

Range: 0:00 - 3:20 (minutes:seconds) **Default:** 0 second

Description: Sets a delay after the starter receives a start command, before it starts the motor.

3O – *DC Brake Torque-2*

Range: 20% - 100% **Default:** 20%

Description: Sets the amount of brake torque the EMX4i will use to slow the motor.

3P – *DC Brake Time-2*

Range: 0:01 - 0:30 (minutes:seconds) **Default:** 1 second

Description: Sets the duration for DC injection during a braking stop.

3Q – *Brake Current Limit-2*

Range: 100% - 600% FLC **Default:** 250%

Description: Sets the current limit for soft brake.

3R – *Soft Brake Delay-2*

Range: 400 - 2000 (milliseconds) **Default:** 400 milliseconds

Description: Sets the time the soft starter will wait after a stop signal is received, before it begins to supply braking current to the motor. Set to allow time for K1 and K2 to switch.

9.8 4 Auto-Start/Stop

The EMX4i can be configured to automatically start and/or stop the motor once per day. For auto-start/stop to operate:

- parameter 4A *Auto-Start/Stop Mode* must be set to 'Enable'
- parameter 1A *Command Source* must be set to 'Clock'
- the reset input must be closed
- the start input (11, 12) must be active. This allows the EMX4i to be stopped via the digital inputs in an emergency.
- parameters 4B ~ 4V: Set as required.

4A – *Auto-Start/Stop Mode*

Options: Disable (default)
Enable

Description: Enable or disable auto-start/stop operation.

4B – *Sunday Mode*

Options:	Start/Stop Disable (default)	Disables auto-start/stop control. Any times scheduled in parameters 4C or 4D will be ignored.
	Start Only Enable	Enables auto-start control. Any auto-stop times scheduled in parameter 4D will be ignored.
	Stop Only Enable	Enables auto-stop control. Any auto-start times scheduled in parameter 4C will be ignored.
	Start/Stop Enable	Enables auto-start and auto-stop control.

Description: Enables or disables auto-start/stop for Sunday.

4C – *Sunday Start Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-start time for Sunday (24 hour format).

4D – *Sunday Stop Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-stop time for Sunday (24 hour format).

4E – *Monday Mode*

Options: Start/Stop Disable (default) Stop Only Enable
Start Only Enable Start/Stop Enable

Description: Enables or disables auto-start/stop for Monday.

4F – *Monday Start Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-start time for Monday (24 hour format).

4G – *Monday Stop Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-stop time for Monday (24 hour format).

4H – *Tuesday Mode*

Options: Start/Stop Disable (default) Stop Only Enable
Start Only Enable Start/Stop Enable

Description: Enables or disables auto-start/stop for Tuesday.

4I – *Tuesday Start Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-start time for Tuesday (24 hour format).

4J – *Tuesday Stop Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-stop time for Tuesday (24 hour format).

4K – *Wednesday Mode*

Options: Start/Stop Disable (default) Stop Only Enable
Start Only Enable Start/Stop Enable

Description: Enables or disables auto-start/stop for Wednesday.

4L – *Wednesday Start Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-start time for Wednesday (24 hour format).

4M – *Wednesday Stop Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-stop time for Wednesday (24 hour format).

4N – *Thursday Mode*

Options: Start/Stop Disable (default) | Stop Only Enable | Start Only Enable | Start/Stop Enable

Description: Enables or disables auto-start/stop for Thursday.

4O – *Thursday Start Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-start time for Thursday (24 hour format).

4P – *Thursday Stop Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-stop time for Thursday (24 hour format).

4Q – *Friday Mode*

Options: Start/Stop Disable (default) | Stop Only Enable | Start Only Enable | Start/Stop Enable

Description: Enables or disables auto-start/stop for Friday.

4R – *Friday Start Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-start time for Friday (24 hour format).

4S – *Friday Stop Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-stop time for Friday (24 hour format).

4T – *Saturday Mode*

Options: Start/Stop Disable (default) | Stop Only Enable | Start Only Enable | Start/Stop Enable

Description: Enables or disables auto-start/stop for Saturday.

4U – *Saturday Start Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-start time for Saturday (24 hour format).

4V – *Saturday Stop Time*

Range: 00:00 - 23:59 **Default:** 00:00

Description: Sets the auto-stop time for Saturday (24 hour format).

9.9 5 Protection Levels

5A – *Current Imbalance*

Range: 10% - 50% **Default:** 30%

Description: Sets the trip point for current imbalance protection.

5B – *Current Imbalance Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 3 seconds

Description: Slows the EMX4i's response to current imbalance, avoiding trips due to momentary fluctuations.

5C – *Undercurrent*

Range: 0% - 100% **Default:** 20%

Description: Sets the trip point for undercurrent protection, as a percentage of motor full load current. Set to a level between the motor's normal working range and the motor's magnetising (no load) current (typically 25% to 35% of full load current). A setting of 0% disables undercurrent protection.

5D – *Undercurrent Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 5 seconds

Description: Slows the EMX4i's response to undercurrent, avoiding trips due to momentary fluctuations.

5E – *Overcurrent*

Range: 80% - 600% **Default:** 400%

Description: Sets the trip point for overcurrent protection, as a percentage of motor full load current.

5F – *Overcurrent Delay*

Range: 0:00 - 1:00 (minutes:seconds) **Default:** 0 second

Description: Slows the EMX4i's response to overcurrent, avoiding trips due to momentary overcurrent events.

5G – *Excess Start Time*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 20 seconds

Description: Excess start time is the maximum time the EMX4i will attempt to start the motor. If the motor does not transition to Run mode within the programmed limit, the starter will trip. Set for a period slightly longer than required for a normal healthy start. A setting of 0 disables excess start time protection.

5H – *Restart Delay*

Range: 00:01 - 60:00 (minutes:seconds) **Default:** 10 seconds

Description: The EMX4i can be configured to force a delay between the end of a stop and the beginning of the next start. During the restart delay period, the display shows the time remaining before another start can be attempted.

9.10 6 Protection Action

6A – *Current Imbalance*

Options:	Soft Trip and Log (default)	The soft starter will stop the motor as selected in parameter 2I or 3I *Stop Mode*, then enter trip state. The trip must be reset before the EMX4i can restart.
	Trip Starter	The soft starter will remove power and the motor will coast to stop. The trip must be reset before the EMX4i can restart.
	Warn and Log	The protection will be written to the event log and the display will show a warning message, but the soft starter will continue to operate.
	Log Only	The protection will be written to the event log but the soft starter will continue to operate.

Description: Selects the soft starter's response to each protection. All protection events are written to the event log.

6B – *Undercurrent*

Options:	Soft Trip and Log (default)	Warn and Log
	Trip Starter	Log Only

Description: Selects the soft starter's response to the protection event.

6C – *Overcurrent*

Options:	Soft Trip and Log (default)	Warn and Log
	Trip Starter	Log Only

Description: Selects the soft starter's response to the protection event.

6D – *Excess Start Time*

Options: Soft Trip and Log (default), Warn and Log, Trip Starter, Log Only

Description: Selects the soft starter's response to the protection event.

6E – *Input A Trip*

Options: Soft Trip and Log (default), Warn and Log, Trip Starter, Log Only

Description: Selects the soft starter's response to the protection event.

6F – *Input B Trip*

Options: Soft Trip and Log (default), Warn and Log, Trip Starter, Log Only

Description: Selects the soft starter's response to the protection event.

6G – *Network Communications*

Options: Soft Trip and Log (default), Warn and Log, Trip Starter, Log Only, Stop

Description: Selects the soft starter's response to the protection event. If set to Stop, the EMX4i will perform a soft stop, then can be restarted without a reset.

6H – *Remote Keypad Fault*

Options: Soft Trip and Log (default), Warn and Log, Trip Starter, Log Only

Description: Selects the soft starter's response to the protection event.

6I – *Frequency*

Options: Soft Trip and Log (default), Warn and Log, Trip Starter, Log Only

Description: Selects the soft starter's response to the protection event.

6J – *Motor Overtemperature*

Options: Soft Trip and Log (default), Warn and Log, Trip Starter, Log Only

Description: Selects the soft starter's response to the protection event.

6K – *Motor Thermistor Circuit*

Options: Soft Trip and Log (default), Warn and Log, Trip Starter, Log Only

Description: Selects the soft starter's response to the protection event.

6L – *Shorted SCR Action*

Options: 3-Phase Control Only (default)
PowerThrough

Description: Selects whether the soft starter will allow PowerThrough operation, if the soft starter is damaged on one phase. The soft starter will use two-phase control, allowing the motor to continue operating in critical applications. Refer to *PowerThrough* on page 41 for further information.

6M – *Battery/Clock*

Options: Soft Trip and Log (default) Warn and Log
Trip Starter Log Only

Description: Selects the soft starter's response to the protection event.

6N – *Pressure Sensor*

Options: Soft Trip and Log (default) Warn and Log
Trip Starter Log Only

Description: Selects the soft starter's response to the protection event.

6O – *Flow Sensor*

Options: Soft Trip and Log (default) Warn and Log
Trip Starter Log Only

Description: Selects the soft starter's response to the protection event.

6P – *Depth Sensor*

Options: Soft Trip and Log (default) Warn and Log
Trip Starter Log Only

Description: Selects the soft starter's response to the protection event.

6Q – *High Pressure*

Options: Soft Trip and Log (default) Warn and Log
Trip Starter Log Only

Description: Selects the soft starter's response to the protection event.

6R – *Low Pressure*

Options: Soft Trip and Log (default) Warn and Log
Trip Starter Log Only

Description: Selects the soft starter's response to the protection event.

6S – *High Flow*

Options:	Soft Trip and Log (default)	Warn and Log
	Trip Starter	Log Only
Description:	Selects the soft starter's response to the protection event.	

6T – *Low Flow*

Options:	Soft Trip and Log (default)	Warn and Log
	Trip Starter	Log Only
Description:	Selects the soft starter's response to the protection event.	

6U – *Flow Switch*

Options:	Soft Trip and Log (default)	Warn and Log
	Trip Starter	Log Only
Description:	Selects the soft starter's response to the protection event.	

6V – *Well Depth*

Options:	Soft Trip and Log (default)	Warn and Log
	Trip Starter	Log Only
Description:	Selects the soft starter's response to the protection event.	

9.11 7 Inputs

7A – *Input A Function*

Options:	Command Override: Network	Overrides the setting of 1A and sets the command source to the communications network.
	Command Override: Digital	Overrides the setting of 1A and sets the command source to the digital inputs.
	Command Override: Keypad	Overrides the setting of 1A and sets the command source to the remote keypad.
	Input Trip (N/O) (default)	A closed circuit across 13, 14 trips the soft starter.
	Input Trip (N/C)	An open circuit across 13, 14 trips the soft starter.
	Emergency Mode	A closed circuit across 13, 14 activates emergency mode. When the EMX4i receives a start command, it will continue to run until a stop command is received, ignoring all trips and warnings.
	Jog Forward	Activates jog operation in a forward direction.

	Jog Reverse	Activates jog operation in reverse direction.
	Zero Speed Sensor	A closed circuit across 13, 14 indicates to the soft starter that the zero speed detector has opened and the motor has reached a standstill.
	Motor Set Select	A closed circuit across 13, 14 instructs the starter to use the secondary motor configuration for the next start/stop cycle.

Description: Selects the function of Input A.

7B – *Input A Trip*

Options:	Always Active	A trip can occur at any time when the soft starter is receiving power.
	Operating Only (default)	A trip can occur while the soft starter is running, stopping or starting.
	Run Only	A trip can only occur while the soft starter is running.

Description: Selects when an input trip can occur.

7C – *Input A Trip Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 0 second

Description: Sets a delay between the input activating and the soft starter tripping.

7D – *Input A Initial Delay*

Range: 00:00 - 30:00 (minutes:seconds) **Default:** 0 second

Description: Sets a delay before an input trip can occur. The initial delay is counted from the time a start signal is received. The state of the input is ignored until the initial delay has elapsed.

7E – *Input B Function*

Options:	Input Trip (N/O) (default)	Jog Reverse
	Input Trip (N/C)	Zero Speed Sensor
	Emergency Mode	Motor Set Select
	Jog Forward	

Description: Selects the function of Input B. Refer to parameter 7A *Input A Function* for details.

7F – *Input B Trip*

Options: Always Active
Operating Only (default)
Run Only

Description: Selects when an input trip can occur.

7G – *Input B Trip Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 0 second

Description: Sets a delay between the input activating and the soft starter tripping.

7H – *Input B Initial Delay*

Range: 00:00 - 30:00 (minutes:seconds) **Default:** 0 second

Description: Sets a delay before an input trip can occur. The initial delay is counted from the time a start signal is received. The state of the input is ignored until the initial delay has elapsed.

7I – *Reset/Enable Logic*

Options: Normally Closed (default)
Normally Open

Description: Selects whether the reset input (10, 11) is normally open or normally closed.

NOTE
If the reset input is active, the starter will not operate.

7J – *Input A Name*

Options: Input A Trip (default)
Custom Message

Description: Selects a message for the keypad to display when Input A is active.

The custom message can be loaded via the USB port. Refer to *USB Save & Load* on page 29 for details.

7K – *Input B Name*

Options: Input B Trip (default)
Custom Message

Description: Selects a message for the keypad to display when Input B is active.

9.12 8 Relay Outputs

8A – *Relay A Function*

Options:	Off	Relay A is not used.
	Ready	The relay is closed when the starter is in Ready state.
	Run (default)	The Run output closes when the soft start is complete (when the starting current falls below 120% of the programmed motor full load current) and remains closed until the beginning of a stop (either soft stop or coast to stop).
	Warning	The relay closes when the starter issues a warning (refer to *6 Protection Action* on page 72).
	Trip	The relay closes when the starter trips (refer to *6 Protection Action* on page 72).
	Low Current Flag	The relay closes when the low current flag activates while the motor is running (refer to parameter 8G *Low Current Flag*).
	High Current Flag	The relay closes when the high current flag activates while the motor is running (refer to parameter 8H *High Current Flag*).
	Motor Temperature Flag	The relay closes when the motor temperature flag activates (refer to parameter 8I *Motor Temperature Flag*).
	Soft Brake Relay	The relay closes when the soft starter receives a stop signal, and remains closed until the end of soft brake.

Description: Selects the function of Relay A. Relay A is a changeover relay.

8B – *Relay A On Delay*

Range: 0:00 - 5:00 (minutes:seconds) **Default:** 0 second

Description: Sets the delay for changing the state of Relay A.

8C – *Relay A Off Delay*

Range: 0:00 - 5:00 (minutes:seconds) **Default:** 0 second

Description: Sets the delay for changing the state of Relay A.

8D – *Relay B Function*

Options:

Off	Low Current Flag
Ready	High Current Flag
Run (default)	Motor Temperature Flag
Warning	Soft Brake Relay
Trip	

Description: Selects the function of Relay B (normally open). Refer to parameter 8A *Relay A Function* for details.

8E – *Relay B On Delay*

Range: 0:00 - 5:00 (minutes:seconds) **Default:** 0 second

Description: Sets the delay for closing Relay B.

8F – *Relay B Off Delay*

Range: 0:00 - 5:00 (minutes:seconds) **Default:** 0 second

Description: Sets the delay for re-opening Relay B.

8G – *Low Current Flag*

The EMX4i has low and high current flags to give early warning of abnormal operation. The current flags can be configured to indicate an abnormal current level during operation, between the normal operating level and the undercurrent or instantaneous overcurrent trip levels. The flags can signal the situation to external equipment via one of the programmable outputs.

The flags clear when the current returns within the normal operating range by 10% of the programmed flag value.

Range: 1% - 100% FLC **Default:** 50%

Description: Sets the level at which the low current flag operates, as a percentage of motor full load current.

8H – *High Current Flag*

Range: 50% - 600% FLC **Default:** 100%

Description: Sets the level at which the high current flag operates, as a percentage of motor full load current.

8I – *Motor Temperature Flag*

The EMX4i has a motor temperature flag to give early warning of abnormal operation. The flag can indicate that the motor is operating above its normal

operating temperature but lower than the overload limit. The flag can signal the situation to external equipment via one of the programmable outputs.

Range: 0% - 160% **Default:** 80%

Description: Sets the level at which the motor temperature flag operates, as a percentage of the motor's thermal capacity.

8J – *Main Contactor Time*

Range: 100 – 2000 milliseconds **Default:** 400 milliseconds

Description: Sets the delay period between the starter switching the main contactor output (terminals 33, 34) and beginning the pre-start checks (before a start) or entering the not ready state (after a stop). Set according to the specifications of the main contactor used.

9.13 9 Analog Output

9A – *Analog Output A*

Options:

Current (% FLC) (default)	Current as a percentage of motor full load current.
Motor Temp (%)	The motor's temperature, calculated by the thermal model.
Heatsink Temperature (°C)	The soft starter's temperature, measured at the heatsink.
Motor pf	Motor power factor, measured by the soft starter.

Description: Selects which information will be reported via the analog output.

9B – *Analog A Scale*

Range: 0-20 mA
4-20 mA (default)

Description: Selects the range of the analog output.

9C – *Analog A Maximum Adjustment*

Range: 0% - 600% **Default:** 100%

Description: Calibrates the upper limit of the analog output to match the signal measured on an external current measuring device.

9D – *Analog A Minimum Adjustment*

Range: 0% - 600% **Default:** 0%

Description: Calibrates the lower limit of the analog output to match the signal measured on an external current measuring device.

9.14 10 Display

10A – *Language*

Options:	English (default)	Português
	Chinese	Français
	Español	Italiano
	Deutsch	Russian

Description: Selects which language the keypad will use to display messages and feedback.

10B – *Temperature Scale*

Options: Celsius (default)
Fahrenheit

Description: Selects whether the EMX4i will display temperatures in degrees Celsius or Fahrenheit.

10C – *Graph Timebase*

Options: 30 seconds (default)
1 minute
30 minutes
1 hour

Description: Sets the graph time scale. The graph will progressively replace the old data with new data.

10D – *Graph Maximum Adjustment*

Range: 0% – 600% **Default:** 400%

Description: Adjusts the upper limit of the performance graph.

10E – *Graph Minimum Adjustment*

Range: 0% – 600% **Default:** 0%

Description: Adjusts the lower limit of the performance graph.

10F – *Current Calibration*

Range: 85% - 115% **Default:** 100%

Description: Calibrates the soft starter's current monitoring circuits to match an external current metering device.

Use the following formula to determine the necessary adjustment:

$$\text{Calibration (\%)} = \frac{\text{Current shown on EMX4i display}}{\text{Current measured by external device}}$$

10G – *Adjustment Lock*

Options:	Read & Write (default)	Allows users to alter parameter values in the Programming Menu.
	Read Only	Prevents users altering parameter values in the Programming Menu. Parameter values can still be viewed.
Description:	Selects whether the keypad will allow parameters to be changed via the Programming Menu.	

10H – *User Parameter 1*

Options:	Blank (default)	Displays no data in the selected area, allowing long messages to be shown without overlapping.
	Motor pf	The motor's power factor, measured by the soft starter.
	Mains Frequency	The average frequency measured on three phases.
	Analog Output Value	The value of the analog output (refer to parameters 9A~9D).
	Motor Temp (%)	The motor's temperature, calculated by the thermal model.
	Heatsink Temperature	The soft starter's temperature, measured at the heatsink.
	Bypass Model (%)	The percentage of thermal capacity remaining in the bypass contactor.
	SCR Temperature	The temperature of the SCRs, calculated by the thermal model.
	Rating Capacity (%)	The thermal capacity available in the soft starter for its next start.
	Number of Starts	The number of starts the EMX4i has completed since the start counter was last reset.
	Hours Run	The number of hours the motor has run via the soft starter.
	Pump Pressure	The pressure at the pump, as configured in parameters 12D~12F. This information is only available if the smart card is installed.

Pump Flow	The flow at the pump, as configured in parameters 12H~12M. This information is only available if the smart card is installed.
Well Depth	The depth of the well, as configured in parameters 12O~12Q. This information is only available if the smart card is installed.
Pump Temperature	The pump temperature, as measured by the PT100. This information is only available if the smart card is installed.

Description: Selects which information will be displayed on the programmable monitoring screen.

10I – *User Parameter 2*

Options:

Blank (default)	Rating Capacity (%)
Motor pf	Number of Starts
Mains Frequency	Hours Run
Analog Output Value	Pump Pressure
Motor Temp (%)	Pump Flow
Heatsink Temperature	Well Depth
Bypass Model (%)	Pump Temperature
SCR Temperature	

Description: Selects which information will be displayed on the programmable monitoring screen. Refer to parameter 10H *User Parameter 1* for details.

9.15 11 Communications Adapter

11A – *Modbus Address*

Range: 1 - 247 **Default:** 1

Description: Sets the Modbus RTU network address for the soft starter.

11B – *Modbus Baud Rate*

Options:
4800
9600 (default)
19200
38400

Description: Selects the baud rate for Modbus RTU communications.

11C – *Modbus Parity*

Options:
None (default)
Odd
Even
10-bit

Description: Selects the parity for Modbus RTU communications.

11D – *Modbus Timeout*

Options:
Off (default)
10 seconds
60 seconds
100 seconds

Description: Selects the timeout for Modbus RTU communications.

11E – *Devicenet Address*

Range: 0 - 63 **Default:** 0

Description: Sets the DeviceNet network address for the soft starter.

11F – *Devicenet Baud Rate*

Options:
125 kB (default)
250 kB
500 kB

Description: Selects the baud rate for DeviceNet communications.

11G – *Profibus Address*

Range: 1 - 125 **Default:** 1

Description: Sets the Profibus network address for the soft starter.

11H – *Gateway Address*

Range: 0 - 255 **Default:** 192

Description: Sets the first component of the network gateway address. The gateway address is set using parameters 11H~11K and the default address is 192.168.0.100.

11I – *Gateway Address* 2

Range: 0 - 255 **Default:** 168

Description: Sets the second component of the network gateway address.

11J – *Gateway Address* 3

Range: 0 - 255 **Default:** 0

Description: Sets the third component of the network gateway address.

11K – *Gateway Address* 4

Range: 0 - 255 **Default:** 100

Description: Sets the fourth component of the network gateway address.

NOTE

The network address can also be set via the Network Address options in the Setup Tools. Refer to *Network Address* on page 32 for details.

11L – *IP Address*

Range: 0 - 255 **Default:** 192

Description: Sets the first component of the soft starter's IP address, for Ethernet communications. The IP address is set using parameters 11L~11O and the default address is 192.168.0.2.

11M – *IP Address* 2

Range: 0 - 255 **Default:** 168

Description: Sets the second component of the soft starter's IP address, for Ethernet communications.

11N – *IP Address* 3

Range: 0 - 255 **Default:** 0

Description: Sets the third component of the soft starter's IP address, for Ethernet communications.

11O – *IP Address* 4

Range: 0 - 255 **Default:** 2

Description: Sets the fourth component of the soft starter's IP address, for Ethernet communications.

NOTE
The network address can also be set via the Network Address options in the Setup Tools. Refer to *Network Address* on page 32 for details.

11P – *Subnet Mask*

Range: 0 - 255 **Default:** 255

Description: Sets the first component of the network subnet mask, for Ethernet communications. The subnet mask is set using parameters 11P~11S and the default mask is 255.255.255.0.

11Q – *Subnet Mask* 2

Range: 0 - 255 **Default:** 255

Description: Sets the second component of the network subnet mask, for Ethernet communications.

11R – *Subnet Mask* 3

Range: 0 - 255 **Default:** 255

Description: Sets the third component of the network subnet mask, for Ethernet communications.

11S – *Subnet Mask* 4

Range: 0 - 255 **Default:** 0

Description: Sets the fourth component of the network subnet mask, for Ethernet communications.

NOTE
The network address can also be set via the Network Address options in the Setup Tools. Refer to *Network Address* on page 32 for details.

11T – *DHCP*

Options: Disable (default)
Enable

Description: Selects whether the communications adapter will accept an IP address assigned by DHCP.

NOTE
DHCP addressing is available with Modbus TCP and Ethernet/IP. DHCP addressing is not supported with Profinet.

11U – *Location ID*

Range: 0 - 65535 **Default:** 0

Description: Sets the soft starter's unique location ID.

9.16 12 Pump Input Configuration

NOTE
The parameters in this group are only active if a smart card is installed.

12A – *Auto-Reset Count*

Range: 0 – 5 **Default:** 0

Description: Sets how many times the soft starter will auto-reset, if it continues to trip. The reset counter increases by one each time the soft starter auto-resets, and resets to zero after a successful start.

12B – *Auto-Reset Delay*

Range: 0:05 - 15:00 (minutes:seconds) **Default:** 5 seconds

Description: Sets a delay before the EMX4i will auto-reset a trip.

12C – *Pressure Sensor Type*

Options: None (default)
Switch
Analog

Description: Selects which type of sensor is associated with the pressure sensor input on the smart card.

12D – *Pressure Units*

Options: Bar
kPa (default)
Psi

Description: Selects which units the sensor will use to report the measured pressure.

12E – *Pressure at 4 mA*

Range: 0 – 500 **Default:** 0

Description: Calibrates the soft starter to the 4 mA (0%) level of the pressure sensor input.

12F – *Pressure at 20 mA*

Range: 0 – 35 **Default:** 0

Description: Calibrates the soft starter to the 20 mA (100%) level of the pressure sensor input.

12G – *Flow Sensor Type*

Options:	None (default)	Pulses per minute
	Switch	Pulses per unit
	Analog	
Description:	Selects which type of sensor is associated with the flow sensor input on the smart card.	

12H – *Flow Units*

Options:	litres/second (default) litres/minute gallons/second gallons/minute
Description:	Selects which units the sensor will use to report the measured flow.

12I – *Flow at 4 mA*

Range:	0 – 100	**Default:**	0
Description:	Calibrates the soft starter to the 4 mA (0%) level of the flow sensor input.		

12J – *Flow at 20 mA*

Range:	0 – 100	**Default:**	100
Description:	Calibrates the soft starter to the 20 mA (100%) level of the flow sensor input.		

12K – *Units per Minute at Max Flow*

Range:	0 – 100	**Default:**	100
Description:	Calibrates the soft starter to the maximum flow volume of the flow sensor.		

12L – *Pulses per Minute at Max Flow*

Range:	0 – 100	**Default:**	100
Description:	Calibrates the soft starter to the maximum flow volume of the flow sensor.		

12M – *Units per Pulse*

Range:	0 – 100	**Default:**	0
Description:	Set to match how many units the flow sensor will measure for each pulse.		

12N – *Depth Sensor Type*

Options: None (default)
Switch
Analog

Description: Selects which type of sensor is associated with the depth sensor input on the smart card.

12O – *Depth Units*

Options: metres (default)
feet

Description: Selects which units the sensor will use to report the measured depth.

12P – *Depth at 4 mA*

Range: 0 – 100 **Default:** 0

Description: Calibrates the soft starter to the 4 mA (0%) level of the depth sensor input.

12Q – *Depth at 20 mA*

Range: 0 – 100 **Default:** 100

Description: Calibrates the soft starter to the 20 mA (100%) level of the depth sensor input.

9.17 13 Flow Protection

NOTE
The parameters in this group are only active if a smart card is installed.

Flow protection uses terminals B13,B14 (sensor 1) on the smart card.

13A – *High Flow Trip Level*

Range: 0% – 600% **Default:** 0%

Description: Sets the trip point for high flow protection.

13B – *Low Flow Trip Level*

Range: 0% – 600% **Default:** 0%

Description: Sets the trip point for low flow protection.

13C – *Flow Start Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 3 seconds

Description: Sets a delay before a flow protection trip can occur. The delay is counted from the time a start signal is received. The flow level is ignored until the start delay has elapsed.

13D – *Flow Response Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 3 seconds

Description: Sets a delay between the flow passing the high or low flow trip levels, and the soft starter tripping.

9.18 14 Pressure Protection

NOTE
The parameters in this group are only active if a smart card is installed.

Pressure protection and pressure control use terminals B23, B24 (sensor 2) on the smart card.

14A – *High Pressure Trip Level*

Range: 0% – 600% **Default:** 0%

Description: Sets the trip point for high pressure protection.

14B – *High Pressure Start Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 3 seconds

Description: Sets a delay before a high pressure protection trip can occur. The delay is counted from the time a start signal is received. The pressure is ignored until the start delay has elapsed.

14C – *High Pressure Response Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 3 seconds

Description: Sets a delay between the pressure passing the high pressure trip level, and the soft starter tripping.

14D – *Low Pressure Trip Level*

Range: 0% – 600% **Default:** 0%

Description: Sets the trip point for high pressure protection.

14E – *Low Pressure Start Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 3 seconds

Description: Sets a delay before a low pressure protection trip can occur. The delay is counted from the time a start signal is received. The pressure is ignored until the start delay has elapsed.

14F – *Low Pressure Response Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 3 seconds

Description: Sets a delay between the pressure passing the low pressure trip level, and the soft starter tripping.

9.19 15 Pressure Control

Pressure protection and pressure control use terminals B23, B24 (sensor 2) on the smart card.

NOTE
The parameters in this group are only active if a smart card is installed.

15A – *Pressure Control Mode*

Options:	Off (default)	The EMX4i will not use the pressure sensor to control soft starting.
	Falling Pressure Start	The EMX4i will start when the pressure drops below the level selected in parameter 15B *Start Pressure Level*.
	Rising Pressure Start	The EMX4i will start when the pressure rises above the level selected in parameter 15B *Start Pressure Level*.

Description: Selects how the EMX4i will use data from the pressure sensor to control the motor.

15B – *Start Pressure Level*

Range: 0% – 600% **Default:** 0%

Description: Sets the pressure level to trigger the EMX4i to perform a soft start.

15C – *Start Response Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 3 seconds

Description: Sets a delay between the pressure passing the pressure control start level, and the EMX4i performing a soft start.

15D – *Stop Pressure Level*

Range: 0% – 600% **Default:** 0%

Description: Sets the pressure level to trigger the EMX4i to stop the motor.

15E – *Stop Response Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 3 seconds

Description: Sets a delay between the pressure passing the pressure control stop level, and the EMX4i stopping the motor.

9.20 16 Depth Protection

NOTE
The parameters in this group are only active if a smart card is installed.

Depth protection uses terminals B33, B34 (sensor 3) on the smart card.

16A – *Depth Trip Level*

Range: 0% – 600% **Default:** 0%

Description: Sets the trip point for depth protection.

16B – *Depth Reset Level*

Range: 0% – 600% **Default:** 0%

Description: Sets the level for the EMX4i to auto-reset a depth trip.

16C – *Depth Start Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 3 seconds

Description: Sets a delay before a depth protection trip can occur. The delay is counted from the time a start signal is received. The depth input is ignored until the start delay has elapsed.

16D – *Depth Response Delay*

Range: 0:00 - 4:00 (minutes:seconds) **Default:** 3 seconds

Description: Sets a delay between the depth passing the depth protection trip level, and the soft starter tripping.

9.21 17 Thermal Protection

NOTE
The parameters in this group are only active if a smart card is installed.

17A – *Temperature Sensor Type*

Options: None (default)
PT100

Description: Selects which type of sensor is associated with the temperature sensor input on the smart card.

17B – *Temperature Trip Level*

Range: 0° – 100° **Default:** 30°

Description: Sets the trip point for temperature protection. Use parameter 10B *Temperature Scale* to configure the temperature scale.

9.22 20 Advanced

20A – *Tracking Gain*

Range: 1% - 200% **Default:** 50%

Description: Fine-tunes the behaviour of the adaptive control algorithm.

20B – *Pedestal Detect*

Range: 0% - 200% **Default:** 80%

Description: Adjusts the behaviour of the adaptive control algorithm for soft stop.

20C – *Bypass Contactor Delay*

Range: 100 – 2000 milliseconds **Default:** 150 milliseconds

Description: Sets the starter to match the bypass contactor closing/opening time. Set according to the specifications of the bypass contactor used. If this time is too short, the starter will trip.

20D – *Current Rating*

Range: Model 1 ~ Model 23 **Default:** Model dependent

Description: Configures the behaviour of the power control PCB to match the operating range of the soft starter. This parameter should only be adjusted when replacing a faulty power control PCB.

NOTE
This parameter can only be adjusted by authorised servicing agents.

20E – *Screen Timeout*

Options:
1 minute (default)
2 minutes
3 minutes
4 minutes
5 minutes

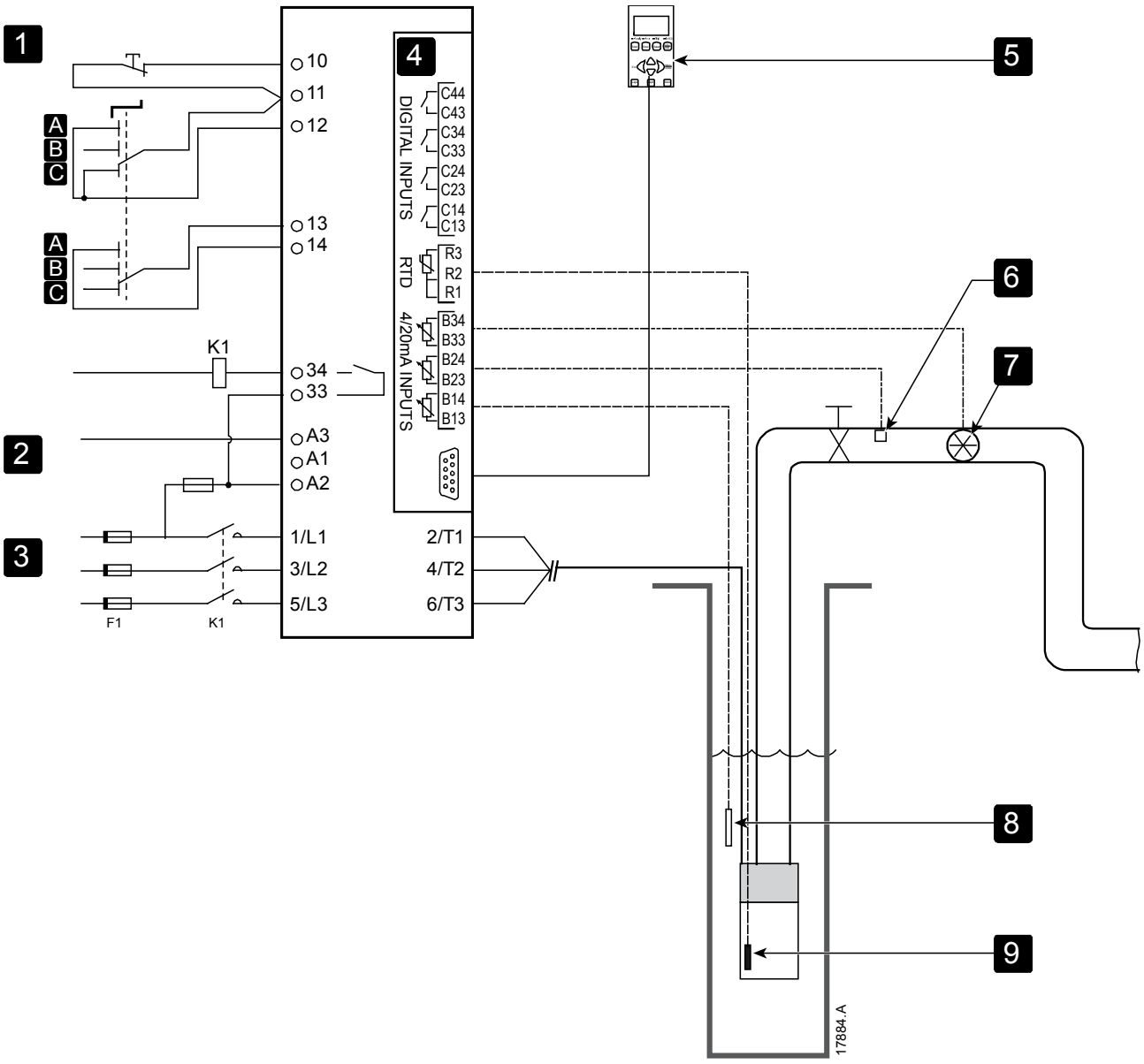
Description: Sets the timeout for the menu to automatically close if no keypad activity is detected.

10. Application Examples

10.1 Smart Card - Pump Control and Protection

The EMX4i smart card is ideal for applications with extensive external inputs, such as pumping situations where external sensors provide additional protection to the pump and motor.

In this example, the EMX4i controls a bore pump via scheduled start/stop operation. The control panel is fitted with a three-way selector switch allowing Auto Run, Stop or Manual Run. Three 4-20 mA transducers are used to monitor water depth, pipe pressure and flow.



1	Digital inputs
A	Manual start
B	Manual stop
C	Automatic operation (scheduled start/stop)
2	Control voltage
3	Three-phase supply
4	Smart card
5	Remote keypad (optional)
6	Pressure sensor
7	Flow sensor
8	Depth sensor
9	Temperature sensor

K1	Main contactor
10, 11	Reset input
11, 12	Start/stop input
13, 14	Programmable input A (set = Command Override: Digital)
33, 34	Main contactor output
R1, R2, R3	Motor temperature protection
B33, B34	Flow protection
B23, B24	Pressure protection
B13,B14	Depth protection

Parameter settings:

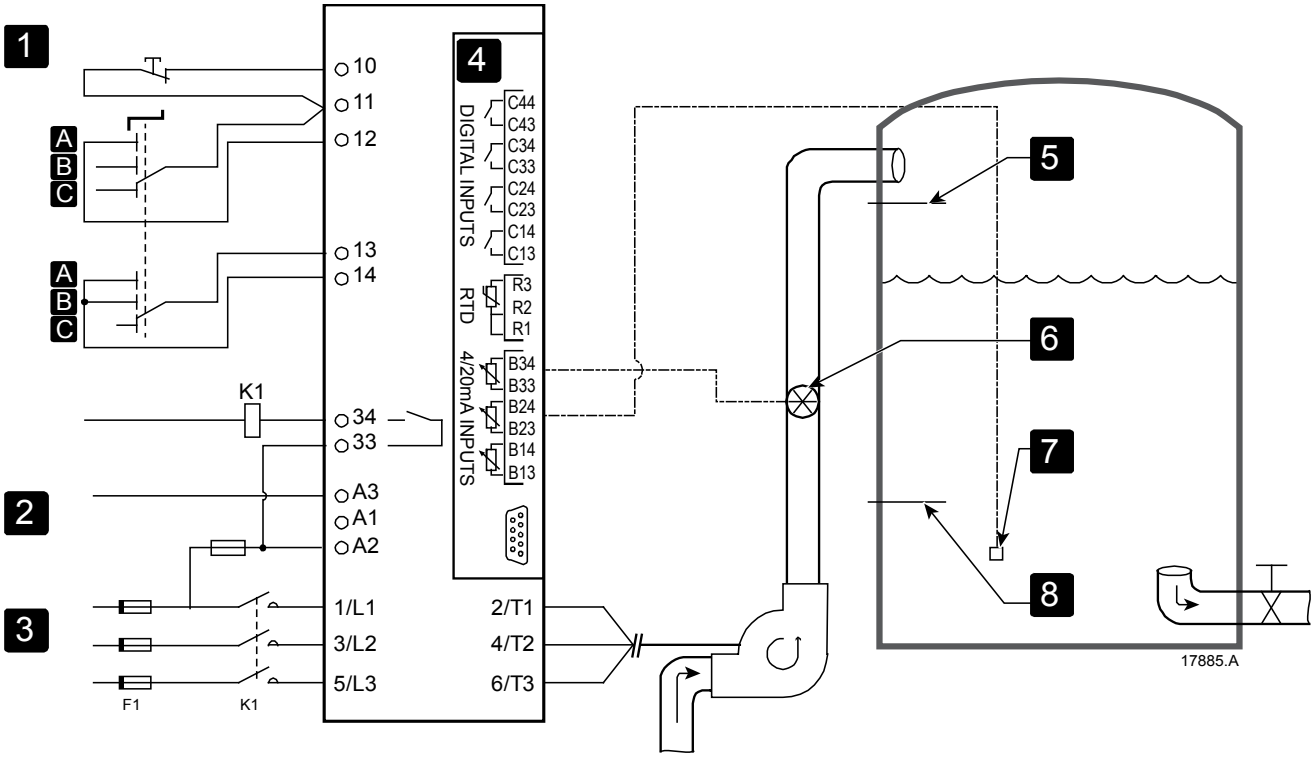
- Parameter 1A *Command Source*: select 'Smart Card + Clock'.
- Parameters 4A~4V Auto-Start/Stop: Set as required.
- Parameter 7A *Input A Function*: select 'Command Override: Digital'.
- Parameters 12A~12Q Pump Input Configuration: Set as required.
- Parameters 13A~13D Flow Protection: Set as required.
- Parameters 14A~14F Pressure Protection: Set as required.
- Parameters 16A~16D Depth Protection: Set as required.
- Parameters 17A~17B Thermal Protection: Set as required.

10.2 Smart Card - Level Controlled Pump Activation

The EMX4i smart card can be used to control start/stop activation of the starter, based on information from external inputs.

In this example, the EMX4i controls a pump which fills a tank, with maximum and minimum water levels. A pressure sensor is used to monitor the level of water in the tank and trigger the pump to fill the tank when water drops below the minimum level, and shut off the pump when the maximum water level is reached.

A three-way selector switch allows the user to override sensor-based control, and manually start or stop the motor.



1	Digital inputs
A	Manual start
B	Manual stop
C	Automatic operation (level-controlled)
2	Control voltage
3	Three-phase supply
4	Smart card
5	Maximum water level
6	Flow sensor
7	Pressure sensor
8	Minimum water level

K1	Main contactor
10, 11	Reset input
11, 12	Start/stop input
13, 14	Programmable input A (set = Command Override: Digital)
33, 34	Main contactor output
B33, B34	Flow protection
B23, B24	Pressure control

Parameter settings:

- Parameter 1A *Command Source*: select 'Smart Card'.
- Parameter 7A *Input A Function*: select 'Command Override: Digital'.
- Parameters 12A~12Q Pump Input Configuration: Set as required.
- Parameters 13A~13D Flow Protection: Set as required.
- Parameters 15A~15E Pressure Control: Set as required.

11. Troubleshooting

11.1 Protection Responses

When a protection condition is detected, the EMX4i will write this to the event log and may also trip or issue a warning. The soft starter's response depends on the Protection Action setting (parameter group 6).

Some protection responses cannot be adjusted by the user. These trips are usually caused by external events (such as phase loss) or by a fault within the soft starter. These trips do not have associated parameters and cannot be set to Warn or Log.

If the EMX4i trips you will need to identify and clear the condition that triggered the trip, then reset the soft starter before restarting. To reset the starter, press the RESET button on the keypad or activate the Reset remote input.

If the EMX4i has issued a warning, the soft starter will reset itself once the cause of the warning has been resolved.

11.2 Trip Messages

Display	Possible cause/Suggested solution
2 Phase - Damaged SCR	This message is displayed if the soft starter tripped on " Lx-Tx shorted" during the pre-start checks and PowerThrough is enabled. It indicates that the starter now operates in PowerThough mode (2-phase control only). Check for either a shorted SCR or a short within the bypass contactor. Related parameters: 6L
Battery/clock	A verification error has occurred on the real time clock, or the backup battery voltage is low. If the battery is low and the power is off, date/time settings will be lost. The EMX4i will continue to soft start and soft stop correctly. Reprogram the date and time. The battery is not removable. In order to replace the battery, the main control PCB must be replaced. Related parameters: 6M
Bypass overload	This trip is not adjustable. Bypass overload protection protects the soft starter from severe operating overloads while running. The soft starter will trip if it detects overcurrent at 600% of the contactor rating. Related parameters: None

Display	Possible cause/Suggested solution
Current imbalance	Current imbalance can be caused by problems with the motor, the environment or the installation, such as: • An imbalance in the incoming mains voltage • A problem with the motor windings • A light load on the motor • A phase loss on input terminals L1, L2 or L3 during Run mode • An SCR that has failed open circuit. A failed SCR can only be definitely diagnosed by replacing the SCR and checking the starter's performance. Related parameters: 5A, 5B, 6A
Current Read Err Lx	Where 'X' is 1, 2 or 3. Internal fault (PCB fault). The output from the CT circuit is not close enough to zero when the SCRs are turned off. Contact your local supplier for advice. Related parameters: None
EEPROM fail	An error occurred loading data from the EEPROM to RAM when the keypad powered up. If the problem persists, contact your local distributor. Related parameters: None
Excess start time	Excess start time trip can occur in the following conditions: • parameter 1B *Motor Full Load Current* is not appropriate for the motor • parameter 2D *Current Limit* has been set too low • parameter 2B *Start Ramp Time* has been set greater than the setting for 5G *Excess Start Time* setting parameter 2B *Start Ramp Time* is set too short for a high inertia load when using Adaptive Control Related parameters: 1B, 2B, 2D, 3B, 3D
Firing Fail Px	Where 'X' is phase 1, 2 or 3. The SCR did not fire as expected. The SCR may be faulty or there may be an internal wiring fault. Related parameters: None
FLC too high	If the soft starter is connected to the motor using inside delta configuration, the soft starter may not be correctly detecting the connection. Contact your local supplier for advice. Related parameters: None

Display	Possible cause/Suggested solution
Flow Switch	The smart card has detected zero flow on sensor 1 (B13,B14). Related parameters: 12G
Frequency	This trip is not adjustable. The mains frequency has gone beyond the specified range. Check for other equipment in the area that could be affecting the mains supply, particularly variable speed drives and switch mode power supplies (SMPS). If the EMX4i is connected to a generator set supply, the generator may be too small or could have a speed regulation problem. Related parameters: 6I
Heatsink overtemperature	• Check that bypass contactors are operating. • Check that cooling fans are operating (models EMX4i-0064B~EMX4i-0580B). • If mounted in an enclosure, check if ventilation is adequate. • The EMX4i must be mounted vertically. Related parameters: None
High Flow	The flow sensor connected to the smart card has activated high flow protection. Related parameters: 13A, 13C, 13D
High Pressure	The pressure sensor connected to the smart card has activated high pressure protection. Related parameters: 12E, 12F, 14A, 14B, 14C
Input A trip Input B trip	The soft starter's programmable input is set to a trip function and has activated. Resolve the trigger condition. Related parameters: 7A, 7B, 7C, 7D, 7E, 7F, 7G, 7H
Instantaneous overcurrent	This trip is not adjustable. The current on all three phases has exceeded 7.2 times the value of parameter 1B *Motor Full Load Current*. Causes can include a locked rotor condition or an electrical fault in the motor or cabling. Related parameters: None
Internal fault x	Where 'X' is a number. This trip is not adjustable. The EMX4i has tripped on an internal fault. Contact your local supplier with the fault code (X).

Display	Possible cause/Suggested solution
Keypad disconnected	Parameter 1A *Command Source* is set to Remote Keypad but the EMX4i cannot detect a remote keypad. If a remote keypad is installed, check the cable is firmly connected to the soft starter. If no remote keypad is installed, change the setting of parameter 1A. Related parameters: 1A
L1 phase loss L2 phase loss L3 phase loss	This trip is not adjustable. During pre-start checks the starter has detected a phase loss as indicated. In run state, the starter has detected that the current on the affected phase has dropped below 2% of the programmed motor FLC for more than 1 second, indicating that either the incoming phase or connection to the motor has been lost. Check the supply and the input and output connections at the starter and at the motor end. Related parameters: None
L1-T1 shorted L2-T2 shorted L3-T3 shorted	During pre-start checks the starter has detected a shorted SCR or a short within the bypass contactor as indicated. Consider using PowerThrough to allow operation until the starter can be repaired. Related parameters: 6L
Low Control Volts	The EMX4i has detected a drop in the internal control voltage. • Check the external control supply (A1, A2, A3) and reset the starter. If the external control supply is stable: • the 24 V supply on the main control PCB may be faulty; or • the bypass driver PCB may be faulty. Contact your local supplier for advice. This protection is not active in Ready state. Related parameters: None
Low Flow	The flow sensor connected to the smart card has activated low flow protection. Related parameters: 13B, 13C, 13D
Low Pressure	The pressure sensor connected to the smart card has activated low pressure protection. Related parameters: 12E, 12F, 14D, 14E, 14F

Display	Possible cause/Suggested solution
Low Water	The depth sensor connected to the smart card has activated depth protection. Related parameters: 12P, 12Q, 16A, 16B, 16C
Motor overload	The motor has reached its maximum thermal capacity. Overload can be caused by: • The soft starter protection settings not matching the motor thermal capacity • Excessive starts per hour or start duration • Excessive current • Damage to the motor windings Resolve the cause of the overload and allow the motor to cool. Related parameters: 1B, 1C, 1D, 1E, 5G, 6D  NOTE Parameters 1C, 1D and 1E determine the trip current for motor overload protection. The default settings of parameters 1C, 1D and 1E provide Motor Overload Protection: Class 10, Trip Current 105% of FLA (full load amperage) or equivalent.
Motor Connection Tx	Where 'X' is 1, 2 or 3. The motor is not connected correctly to the soft starter. • Check individual motor connections to the soft starter for power circuit continuity. • Check connections at the motor terminal box. This trip is not adjustable. Related parameters: None
Motor thermistor	The motor thermistor input has been enabled and: • The resistance at the thermistor input has exceeded 3.6 kΩ for more than one second. • The motor winding has overheated. Identify the cause of the overheating and allow the motor to cool before restarting. • The motor thermistor input has been opened. If thermistors have previously been connected to the EMX4i but are no longer required, use the Thermistor Reset function to disable the thermistor. Related parameters: 6J

Display	Possible cause/Suggested solution
Network communication	There is a network communication problem, or the network master may have sent a trip command to the starter. Check the network for causes of communication inactivity. Related parameters: 6G
Not ready	• The reset input may be active. If the reset input is active, the starter will not operate. • The soft starter may be waiting for the restart delay to elapse. The length of the restart delay is controlled by parameter 5H *Restart Delay*. Related parameters: 5H
Overcurrent	The current has exceeded the level set in parameter 5E *Overcurrent* for longer than the time set in parameter 5F *Overcurrent Delay*. Causes can include a momentary overload condition. Related parameters: 5E, 5F, 6C
Parameter out of range	This trip is not adjustable. • A parameter value is outside the valid range. The keypad will indicate the first invalid parameter. • An error occurred loading data from the EEPROM to RAM when the keypad powered up. • The parameter set or values in the keypad do not match the parameters in the starter. • "Load User Set" has been selected but no saved file is available. Reset the fault. The starter will load the default settings. If the problem persists, contact your local distributor. Related parameters: None Related parameters: None
Phase sequence	Mains voltage must be connected to the soft starter's input terminals (L1, L2, L3) in positive phase sequence. Check the phase sequence on L1, L2, L3. Related parameters: None

Display	Possible cause/Suggested solution
Power loss	This trip is not adjustable. The starter is not receiving mains supply on one or more phases when a Start Command is given. Check that the main contactor closes when a start command is given, and remains closed until the end of a soft stop. Check the fuses. If testing the soft starter with a small motor, it must draw at least 2% of its minimum FLC setting on each phase. Related parameters: None
Rating Capacity	The EMX4i is operating beyond its safe capacity. Allow the starter to cool. Related parameters: None
RTD Circuit	The RTD input on the smart card is open circuit or short circuit. Related parameters: None
SCR Itsm	The SCR current surge rating has been exceeded. Related parameters: None
SCR overtemperature	The temperature of the SCRs, calculated by the thermal model, is too high to allow further operation. Wait for the starter to cool. Related parameters: None
Sensor X	Where 'X' is 1, 2 or 3. The smart card has detected on open circuit on one of the analog inputs. Sensor 1 is B13,B14; sensor 2 is B23, B24; sensor 3 is B33, B34. Related parameters: 12C
Starter communication	There is a problem with the connection between the soft starter and the optional expansion card. Remove and reinstall the card. If the problem persists, contact your local distributor. Related parameters: 6G
Thermistor circuit	The thermistor input has been enabled and: • The resistance at the input has fallen below 20 Ω (the cold resistance of most thermistors will be over this value) or • A short circuit has occurred. Check and resolve this condition. Related parameters: None

Display	Possible cause/Suggested solution
Time-overcurrent	The EMX4i is internally bypassed and has drawn high current during running. (The 10A protection curve trip has been reached or the motor current has risen to 600% of the motor FLC setting.) Related parameters: None
Undercurrent	The motor has experienced a sharp drop in current, caused by loss of load. Causes can include broken components (shafts, belts or couplings), or a pump running dry. Related parameters: 5C, 5D, 6B
Unsupported option	The selected function is not available (eg jog is not supported in inside delta configuration). Related parameters: None
VZC Fail Px	Where 'X' is 1, 2 or 3. Internal fault (PCB fault). Contact your local supplier for advice. Related parameters: None
Zero Speed Detect	The zero speed input has not closed within the expected duration of a soft stop. • Check the zero speed sensor is operating correctly. • Check that parameters 2Q *Brake Current Limit* and 5G *Excess Start Time* are appropriate for the application. Related parameters: 2Q, 3Q, 5G

11.3 General Faults

This table describes situations where the soft starter does not operate as expected but does not trip or give a warning.

Symptom	Probable Cause
Starter "Not Ready"	• The reset input may be active. If the reset input is active, the starter will not operate.
The soft starter does not respond to the START or RESET button on the keypad.	• The soft starter will only accept commands from the keypad if parameter 1A *Command Source* is set to Remote Keypad. Check that the Local LED on the starter is on.

Symptom	Probable Cause
The soft starter does not respond to commands from the control inputs.	• The soft starter will only accept commands from the inputs if parameter 1A *Command Source* is set to Digital Input. Check the setting of 1A. • The control wiring may be incorrect. Check that the remote start, stop and reset inputs are configured correctly (refer to *Start/Stop* on page 20 for details). • The signals to the remote inputs may be incorrect. Test the signalling by activating each input signal in turn.
The soft starter does not respond to a start command from either the local or remote controls.	• The soft starter may be waiting for the restart delay to elapse. The length of the restart delay is controlled by parameter 5H *Restart Delay*. • The motor may be too hot to permit a start. The soft starter will only permit a start when it calculates that the motor has sufficient thermal capacity to complete the start successfully. Wait for the motor to cool before attempting another start. • The reset input may be active. If the reset input is active, the starter will not operate. • The soft starter may be waiting for control signals via the communications network (parameter 1A *Command Source* = Network). • The EMX4i may be waiting for a scheduled auto-start (parameter 1A *Command Source* = Clock).
Erratic and noisy motor operation.	• If the soft starter is connected to the motor using inside delta configuration, the soft starter may not be correctly detecting the connection. Contact your local supplier for advice.
Remote keypad shows message "awaiting data"	The keypad is not receiving data from the control PCB. Check the cable connection.

Symptom	Probable Cause
The soft starter does not control the motor correctly during starting.	• Start performance may be unstable when using a low *Motor Full Load Current* setting (parameter 1B). • Power factor correction (PFC) capacitors must be installed on the supply side of the soft starter and must be disconnected during starting and stopping. To use the EMX4i to control power factor correction, connect the PFC contactor to a programmable relay set to Run. • High levels of harmonics on the mains supply can affect soft starter performance. If variable speed drives are installed nearby, check they are properly grounded and filtered.
Motor does not reach full speed.	• If the start current is too low, the motor will not produce enough torque to accelerate to full speed. The soft starter may trip on excess start time.  NOTE Make sure the motor starting parameters are appropriate for the application and that you are using the intended motor starting profile. If a programmable input is set to Motor Set Select, check that the corresponding input is in the expected state. The load may be jammed. Check the load for severe overloading or a locked rotor situation.
Soft stop ends too quickly.	• The soft stop settings may not be appropriate for the motor and load. Review the soft stop settings. • If the motor is very lightly loaded, soft stop will have limited effect.
After selecting Adaptive Control the motor used an ordinary start and/or the second start was different to the first.	• The first Adaptive Control start is actually 'Constant Current' so that the starter can learn from the motor characteristics. Subsequent starts use Adaptive Control.
PowerThrough does not operate when selected.	• The starter will trip on Lx-Tx Shorted on the first start attempt after control power is applied. PowerThrough will not operate if control power is cycled between starts.

Symptom	Probable Cause
Parameter settings cannot be stored.	• Make sure you are saving the new value by pressing the STORE button after adjusting a parameter setting. If you press EXIT, the change will not be saved. The EMX4i does not display a confirmation. • Check that the adjustment lock (parameter 10G) is set to Read & Write. If the adjustment lock is set to Read Only, settings can be viewed but not changed.
USB Missing	A USB function has been selected in the menu, but the product cannot detect a USB drive. Check that the USB drive has been inserted in the port.
File Missing	A USB function has been selected in the menu, but the required file cannot be found. Save/Load Master Parameters uses a file called Master_Parameters.par, at the top level of the USB drive. For these functions to work correctly, do not move or rename this file.
File Not Valid	A USB function has been selected in the menu, but the file is not valid.
File Empty	A USB function has been selected in the menu and the file has been found, but does not contain the expected content.
Rating Not Valid	The value selected for parameter 20D *Current Rating* does not match the soft starter. Set parameter 20D to match the rating shown on the EMX4i nameplate label (on the side of the unit).

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